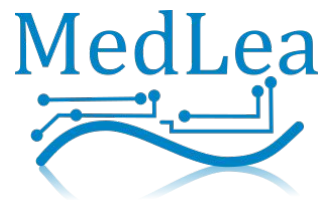


AI for respiratory diagnosis

CHIST-ERA MUCCA WP5



www.medlea-tech.com

MUCCA General Meeting - Liverpool 21/09/2023

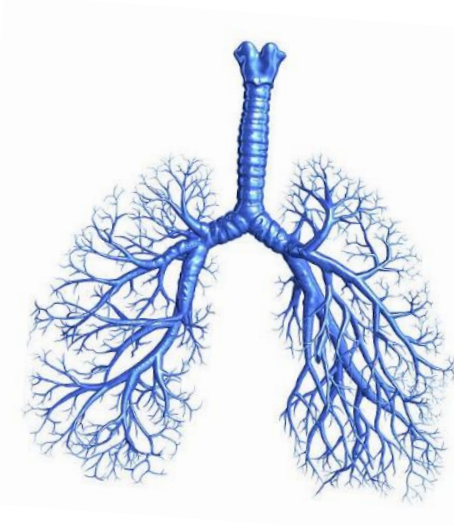
Context

Lungs diseases:

Respiratory diseases hit 10% of population

They are degenerative, largely misdiagnosed or undiagnosed (~30%)

Early diagnosis and prognosis case save lives



Anatomy:

Airways (trachea, bronchi, bronchioles) with 22 generations of bifurcations (2^{22} branches)

Airways are embedded in a tissue (parenchyma) that is filled with alveoli

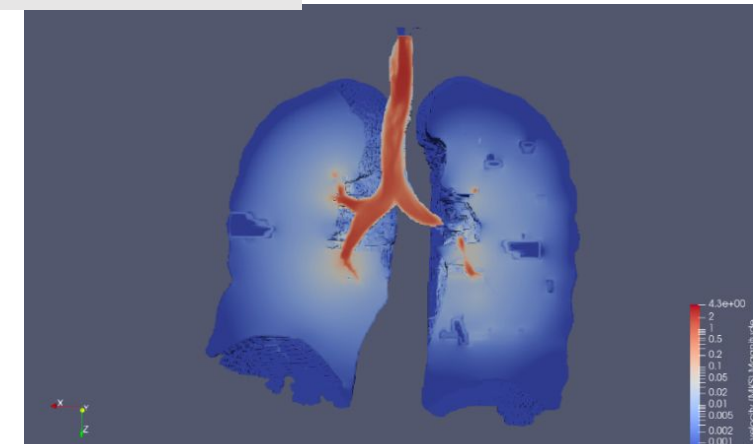
Made of compartments/regions (lobes)

Lungs function like a oscillatory pump and internal resistances make the whole difference

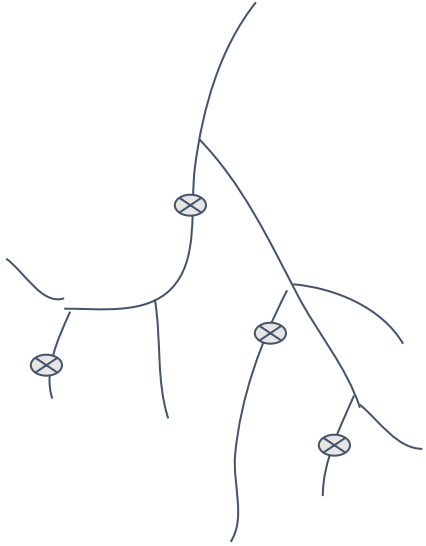
Diagnostic tools:

Morphological: Imaging (CT scans and Rx)

Functional: Spirometry



Systemic failures



Airways:

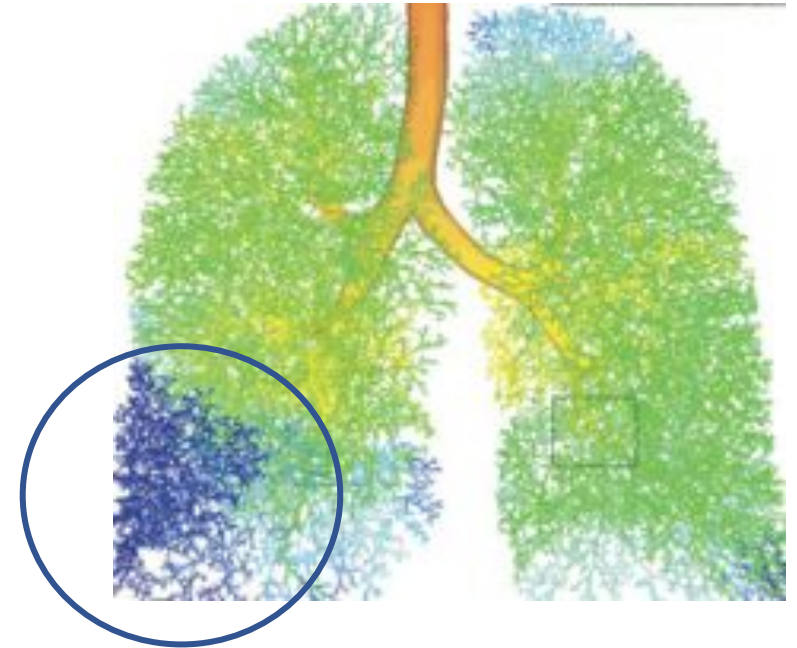
- *Focal or multifocal blockages*
- *Effusions / edema / mucus*
- *Inflammations*



Fibrosis:

- *Low compliance*
- *Gas diffusion / air trapping*
- *Inflammations back to airways*

Asthma, COPD, BOS, etc.



pneumonia, covid, IPF, RAS, etc.

From dyspnea to death

Goals

- *Develop an integrated approach for 3D reconstruction from medical images to perform simulation & experiments on respiratory tracts (airways)*
- *Assess airflow and air+mucus dynamics in respiratory tracts: Newtonian and non-Newtonian rheology*
- *Validate simulation results versus idealized and real data from patients geometries*
Compare with experimental data from Bucharest
- *Reach a high level of automation to handle several geometries (patients)*
- *Feed large dataset to AI to reproduce flow patterns automatically and assess causal relations*



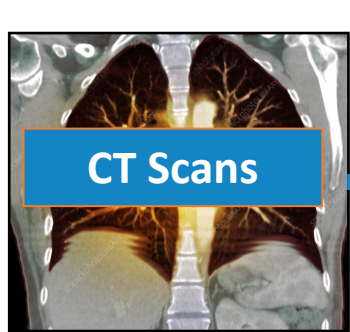
MedLea contribution:

- **WeResp:** *medical images reconstruction*
- **Moebius:** *multiphysics simulator in complex geometries*
- **AI** *for functional analysis*

Description	Year 1				Year2				Year3			
	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4
WP5 MED-2												
T 5.1 Reconstruction on tomographic scans	■	■										
T5.2 Experiments and validation on air-mucus in idealized geometries			■	■								
T5.3 Experiments and validation on air-mucus in respiratory geometries					■	■						
T5.4 Test of xAI on simulation results							■	■	■	■	■	■

Roadmap

Purpose: xAI + high-performance simulation + experiments to diagnose the impact of mucus excess in patient-specific respiratory health with anatomies acquired from tomographic scans.



Non-Linear Response

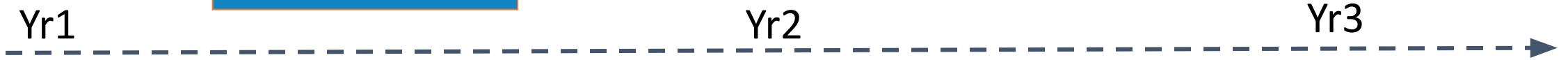
Idealized Geometries

Viscoelastic Rheology Model & Simulations

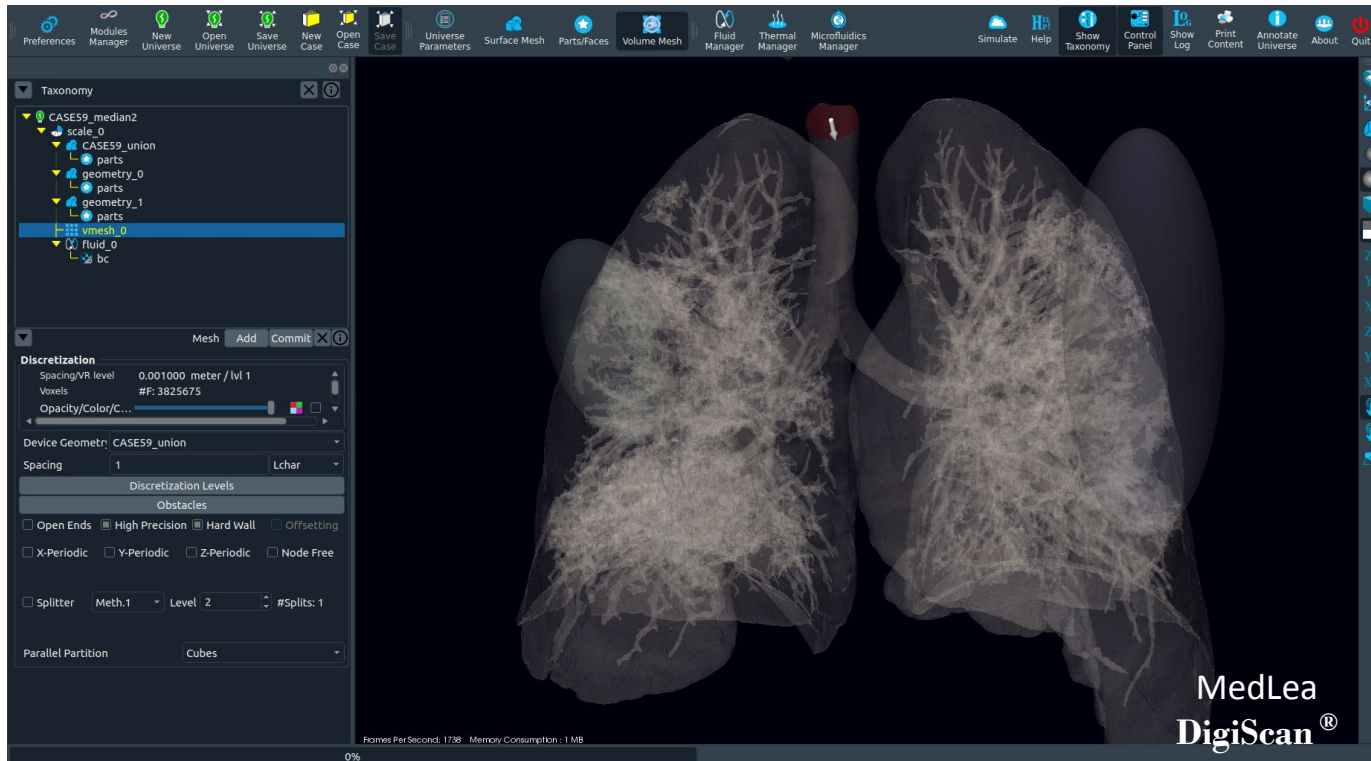
Experiments from Bucharest

xAI

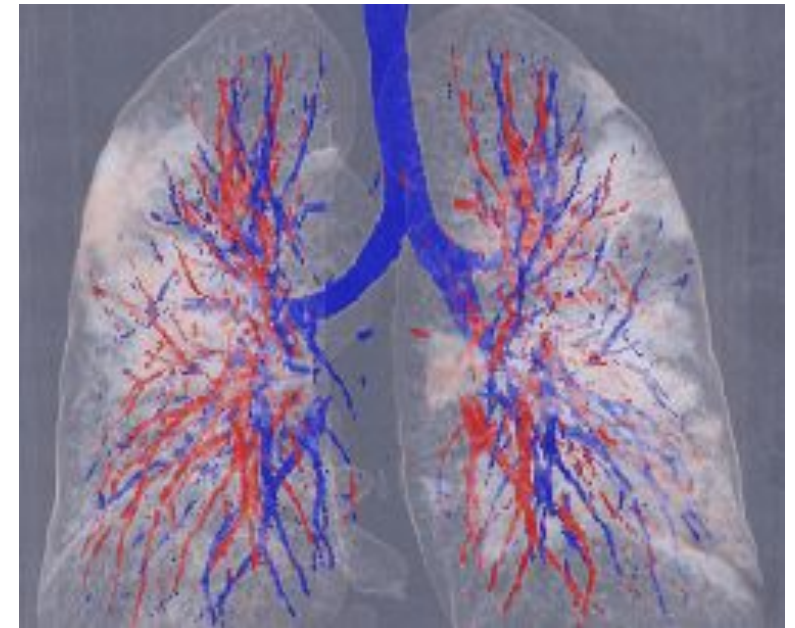
Reparametrization



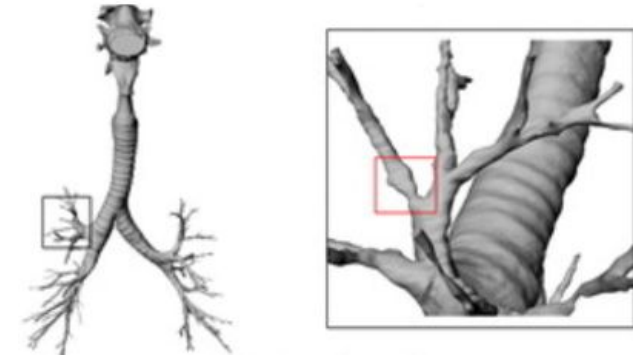
Reconstruction of radiological images



1. CT-derived airways. Focus on airways, not parenchyma
2. Reconstruct airways explicitly up to CT resolution (~1 mm)
3. Complement with synthetic airways obeying Murray's law over generations (self-similarity)



Reconstruct lung tracts automatically
Annotations and metrology
Optimized workflow



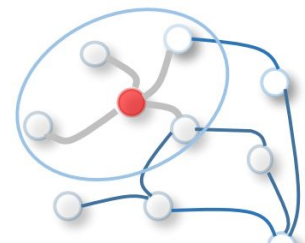
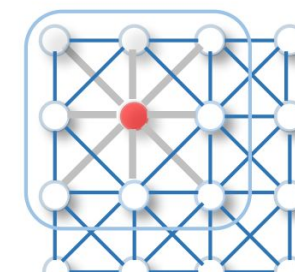
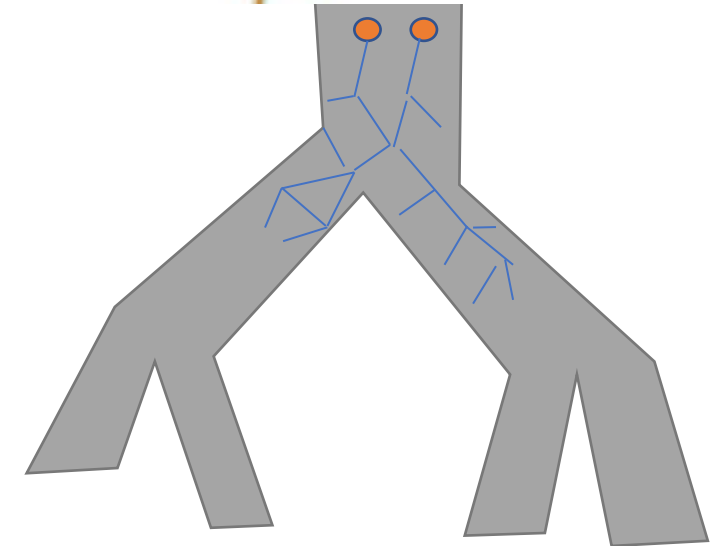
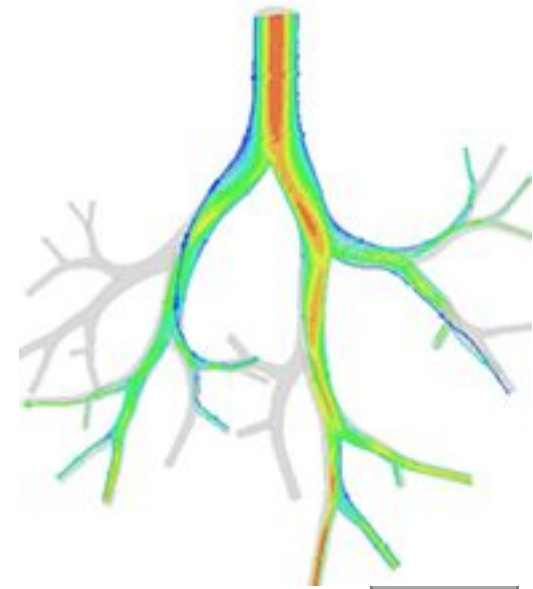
Predicting flows

Goals

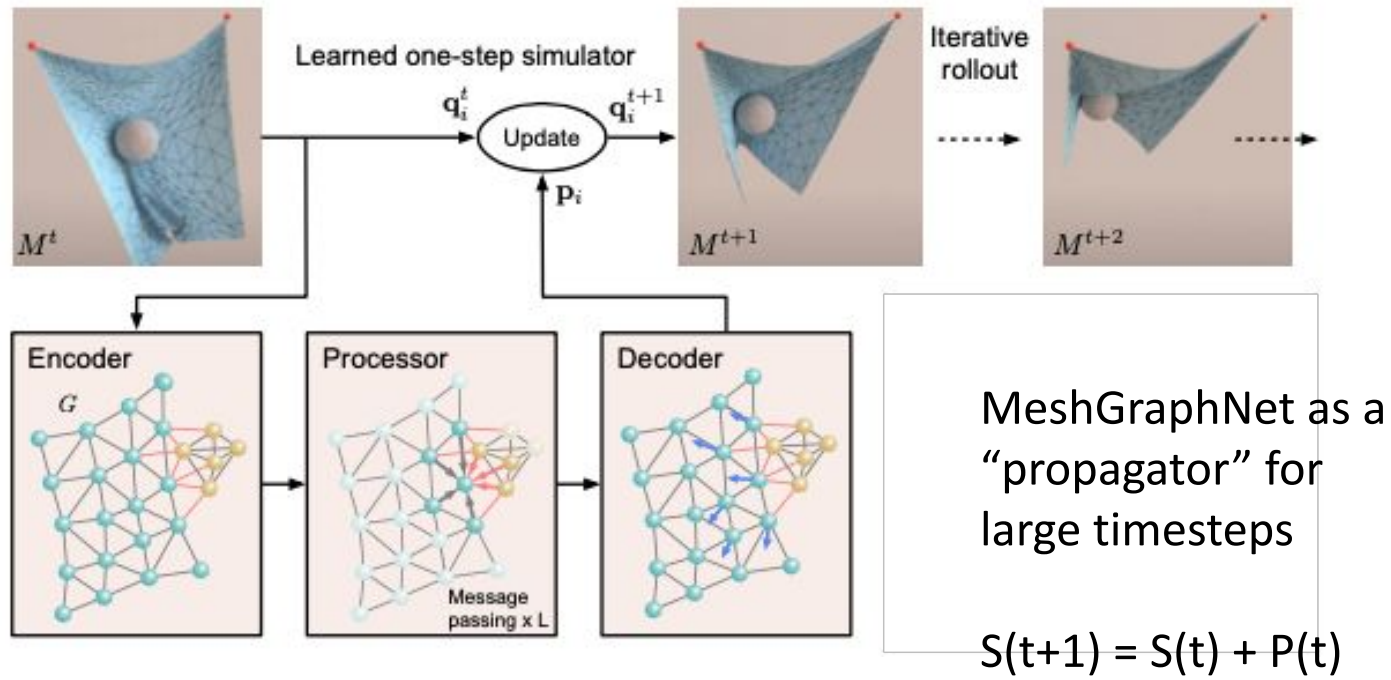
- predict flow distribution at variable Reynolds
- breakdown of 22 generations in bifurcating bricks (1 parent, 2 daughters)
- geometry: from dense to downsampled graphs
- the problem of equivariance (roto-translational symmetries SE3-group)
- Ensure vectors/tensors invariance (eg spherical harmonics basis set)
- Conservations (via Voronoi volumes)

Features

- Flow velocity, pressure, stress tensor
- Minimum distance from walls (to highlight near-wall velocity gradients)
- Maximum inscribed sphere (compress geometrical information and Reynolds proxy)



Propagative approach



Pfaff et al. arXiv 2022

Generated a system of 3D synthetic pipes obeying Murray's self-similarity for lengths/calibers

Randomly chosen angles

Geometrical defects

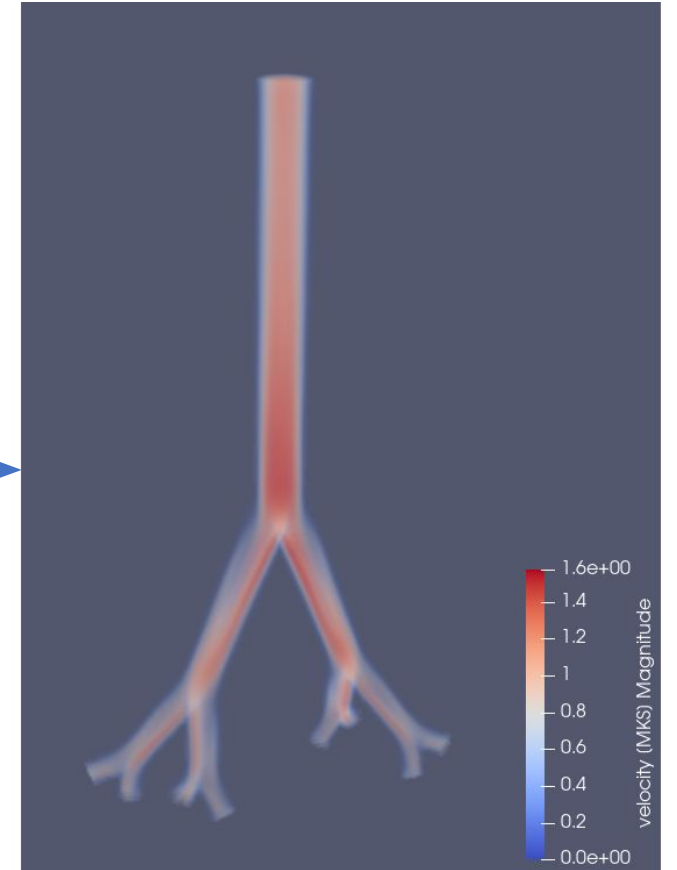
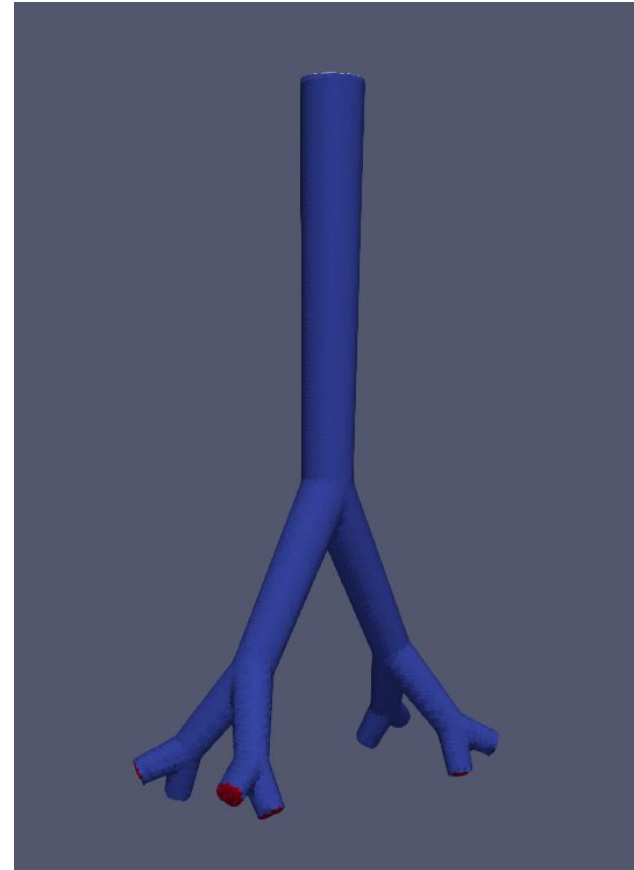
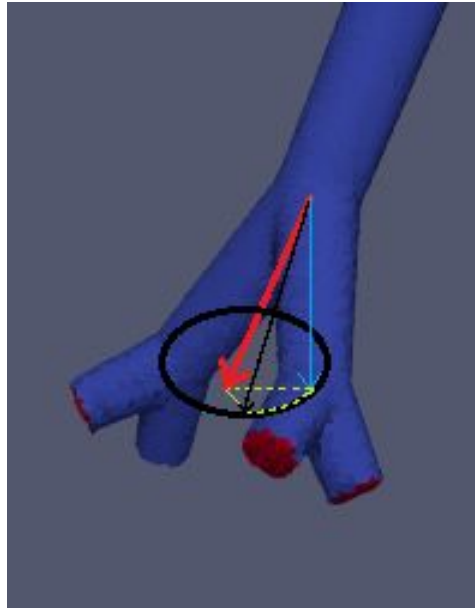
Model geometries

Different approach: develop an AI model able to describe air propagation, starting from simple geometries.

Then we can use a CFD solver on the idealized domain, producing large amounts of data

~100k voxel grids, $\Delta t \sim 10^{-5}$ s

CFD simulation



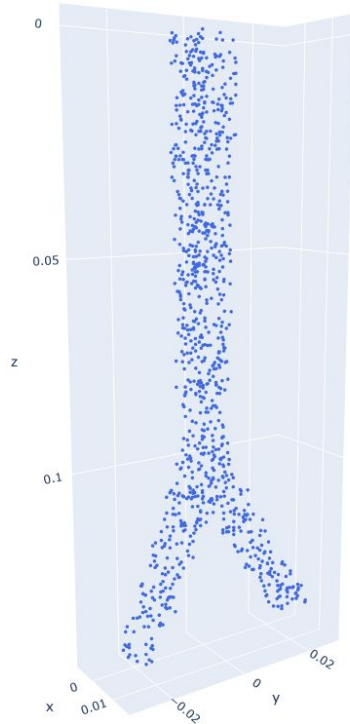
Data production

Several simulations are needed to train our model: **Coarse graining** both in space and time.

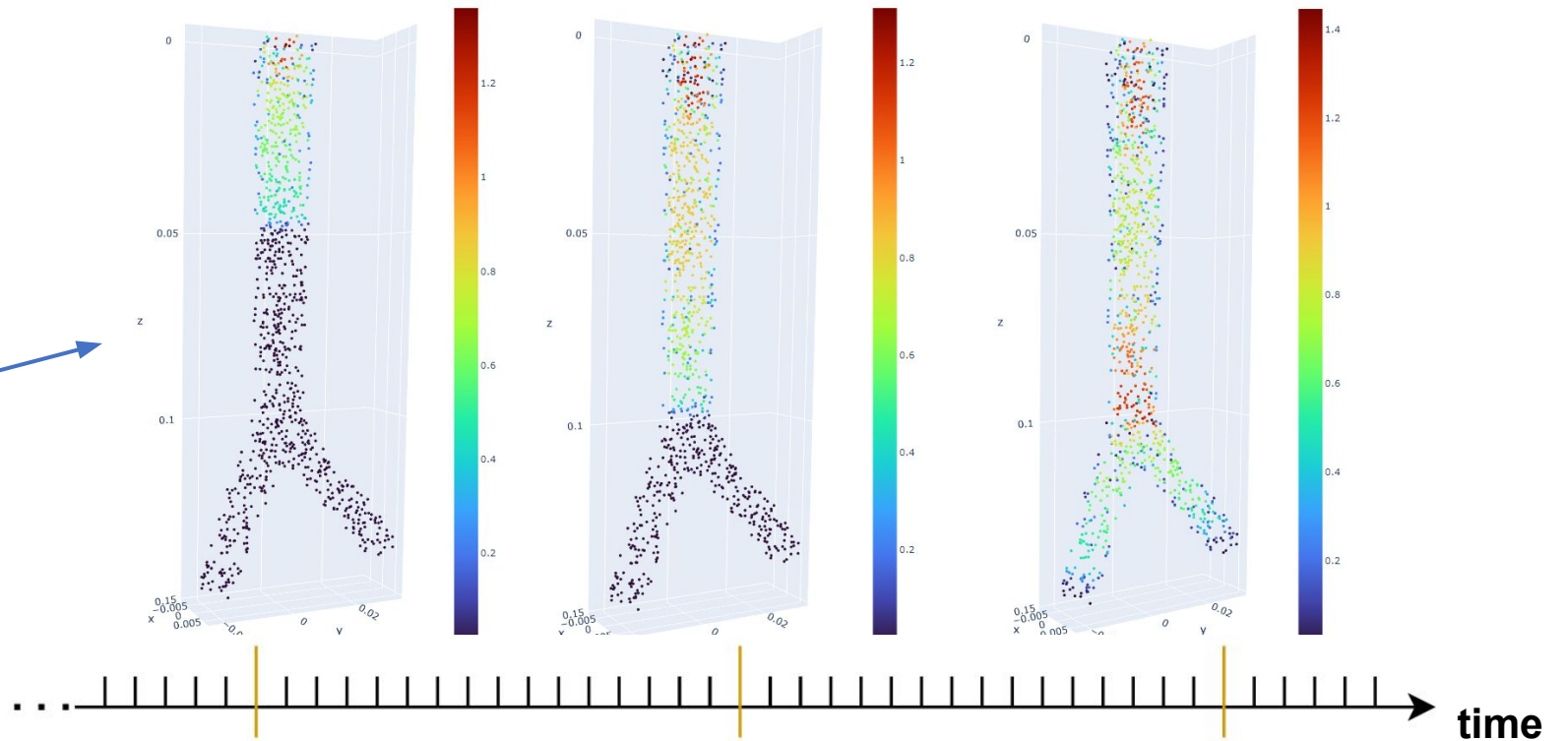
- Uniform random sampling of 1% of nodes
- We retained only one every 20 simulator steps

Information stored on nodes: spatial coordinates (fixed), pressure and velocity components

Extracted probes (point cloud)



Velocity field vs time

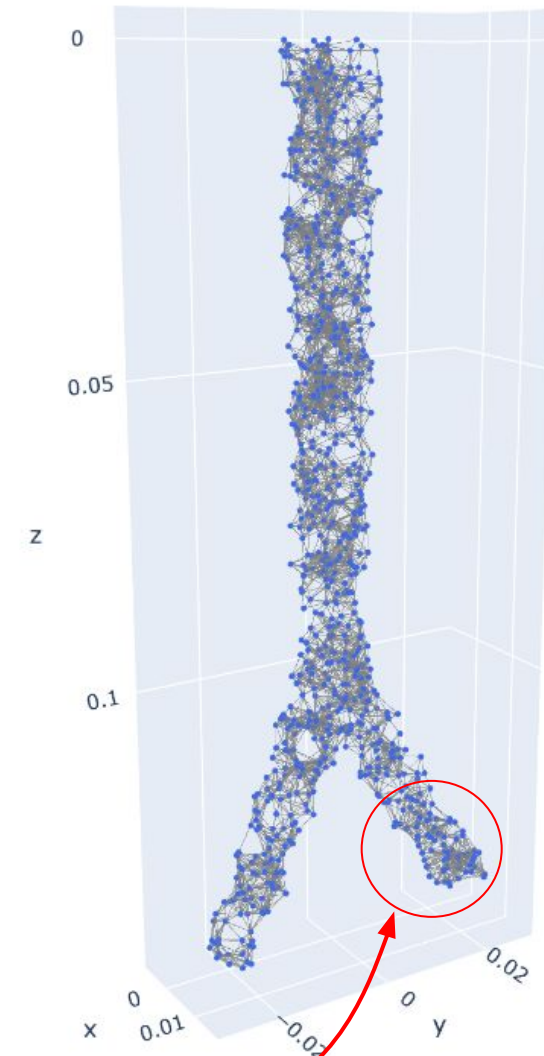
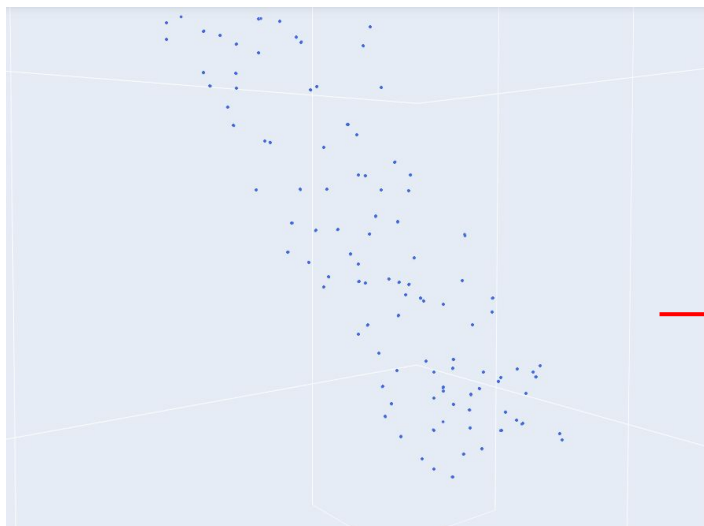


Data production

- Interaction among points modeled as a graph
- Connectivity is produced using a radius nearest neighbours (RNN) algorithm

Dataset production

- We produced 1000 simulations of 500 steps each.
- Every simulation has its own slightly different geometry and unique point cloud.
- All geometries have one bifurcation
- Every 100 simulations, the inlet velocity changes (+/- 20%)



Task identification

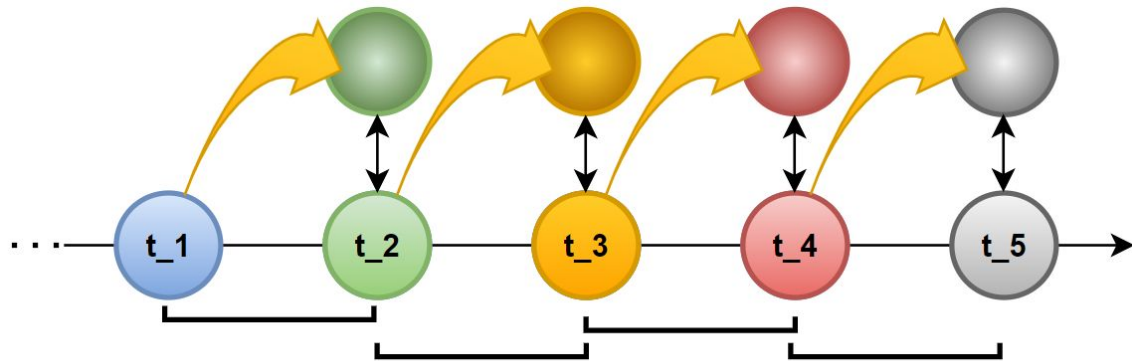
One step propagator:

1. *Input state: P, V at time t*

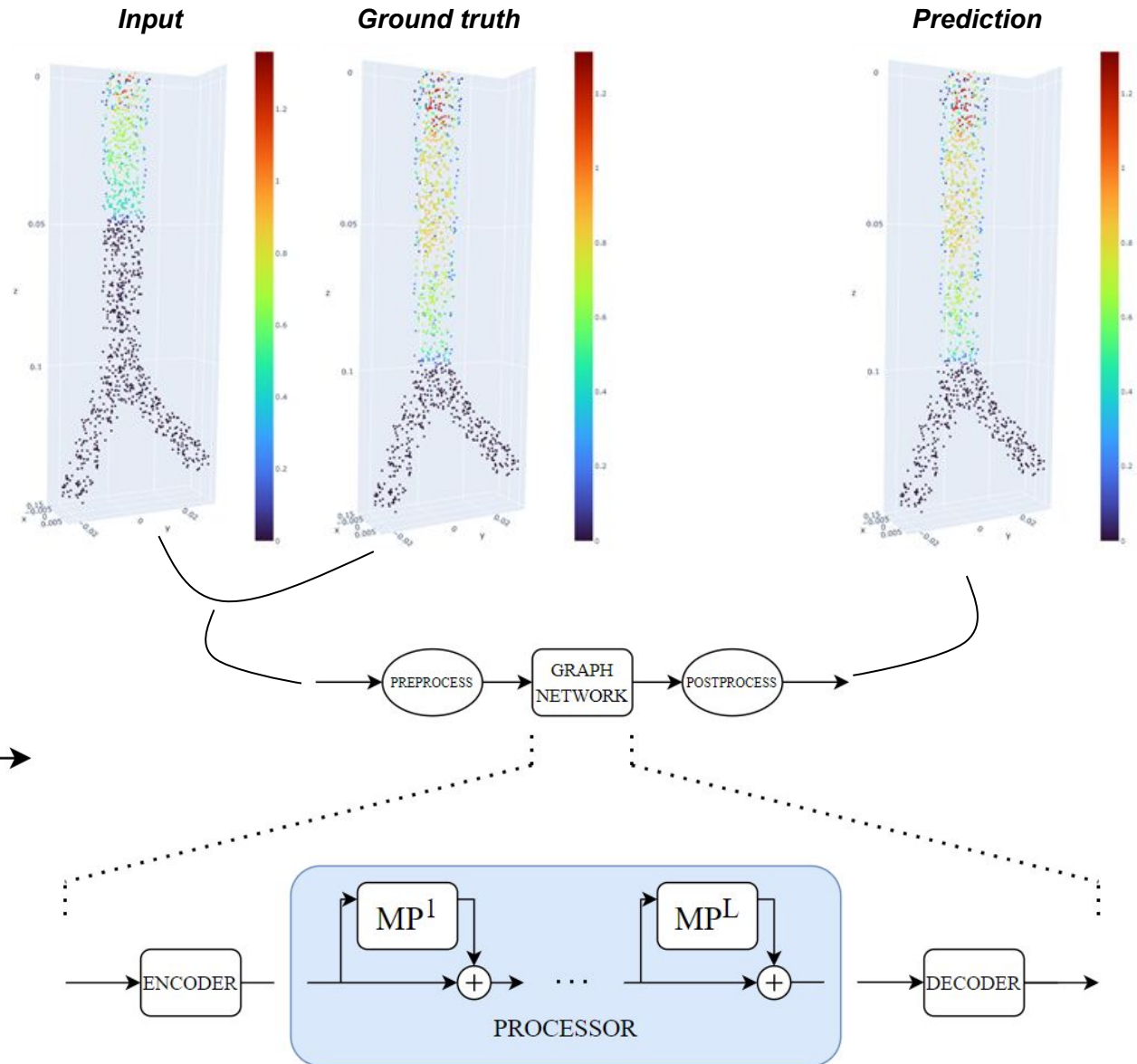
2. *Output state: P, V at time t+Δt*

With window W=1, a simulation of N time frames becomes a set of N-1 pairs

$$\{(t_1, t_2); (t_2, t_3); \dots; (t_{n-1}, t_n)\}$$



Model design¹ →



Multiphase Case

Multiphase Color-LBM scheme

Viscoelastic and multiphase stress tensor are additive components

Stable simulations over complex geometries

Resulting in one set of populations per specie, therefore

Workload for air-mucus is **x100** than for pure air

$$f_p^{*k} = (1 - \omega^k) f_p^k + \omega^k f_p^{eq,k}$$

A lattice Boltzmann method for simulating viscoelastic drops

Cite as: Phys. Fluids 31, 073101 (2019); <https://doi.org/10.1063/1.5100327>
Submitted: 17 April 2019 • Accepted: 11 June 2019 • Published Online: 02 July 2019

Di Wang, Danielle Tan and Nhan Phan-Thien

Multiphase non-elastic response validated under microfluidics settings

Dripping/slug regimes correctly identified

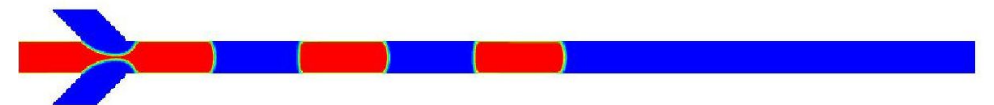
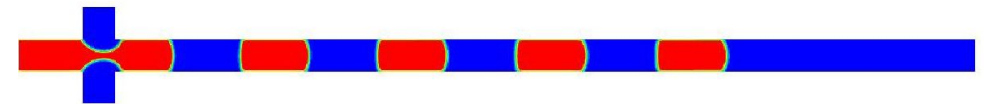
Addition of non-disjoining pressure effects available

Full dynamic response to be validated vs experiments:

- Open flow (1:4 contraction)
- Confinement (branched tubes)



(a)



(b)

ViscoElasticity (effective single-phase)

Tensorial model: 9 components for polymeric specie + solvent

Oldroyd-B model / Other visco-elastic models (FENE)

Fully parallelized with CUDA for GPUs

$$h_{p,ab}(x + hc_p, t + h) = \frac{1}{\tau_D} h_{p,ab}^{eq} + \left(1 - \frac{1}{\tau_D}\right) h_{p,ab} + \frac{G_{ab}}{A_{ab}} h_{p,ab}^{eq}$$

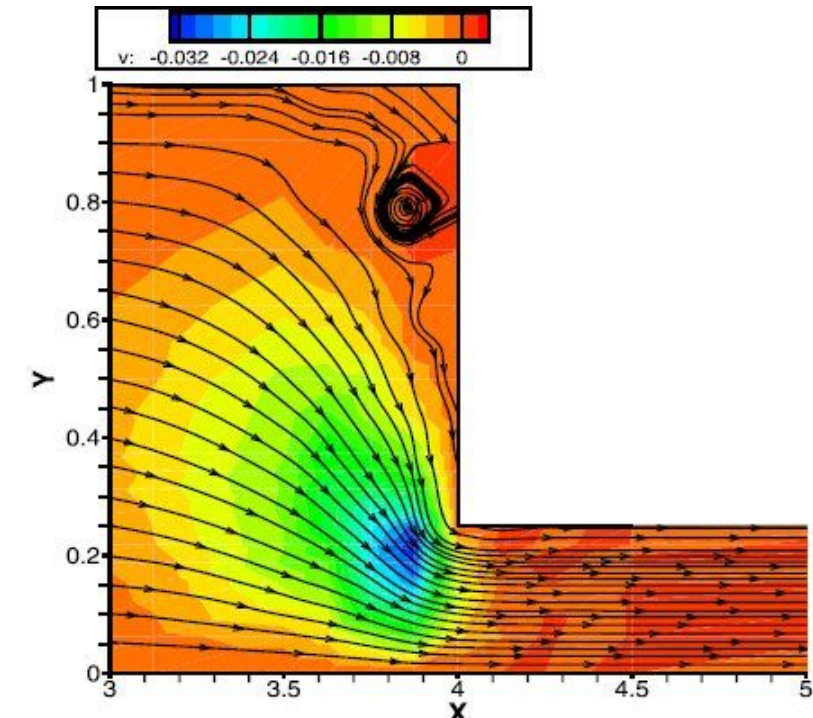
Workload is **x10** than for pure air

The goal is to use GNN to predict viscoelastic dynamics



Lattice Boltzmann method for the simulation of viscoelastic fluid flows

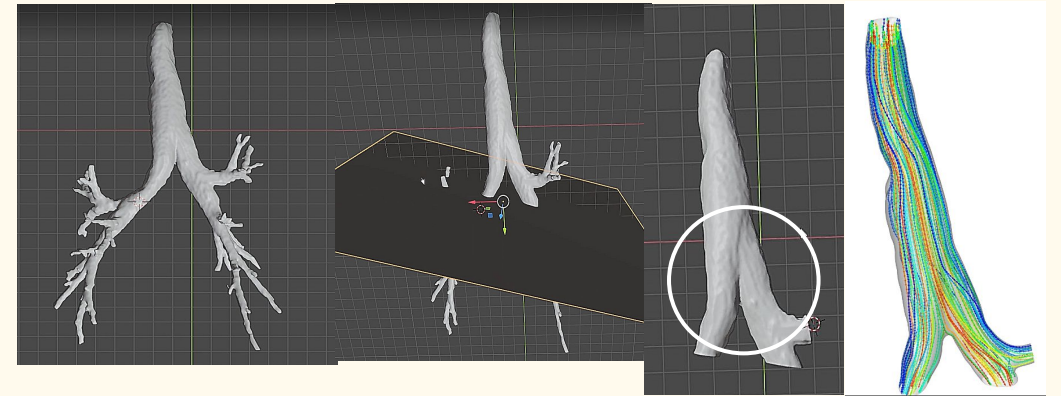
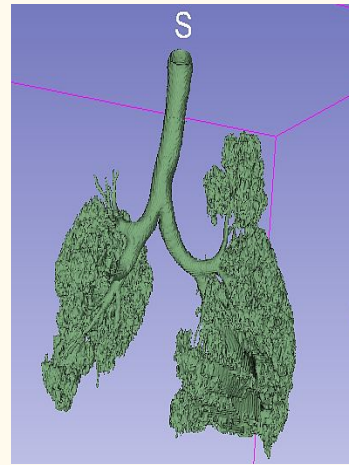
O. Malaspinas ^{a, b}, N. F  tier ^a, M. Deville ^a



Currently under scrutiny for 1:4 contraction

Air-Mucus transport in tracheal model

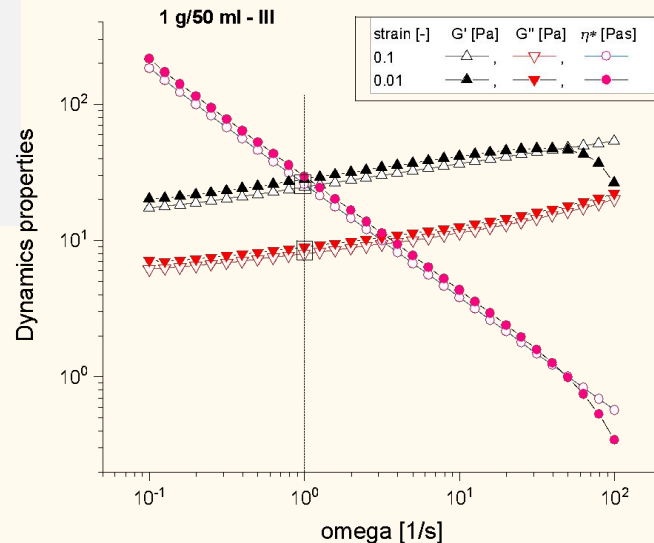
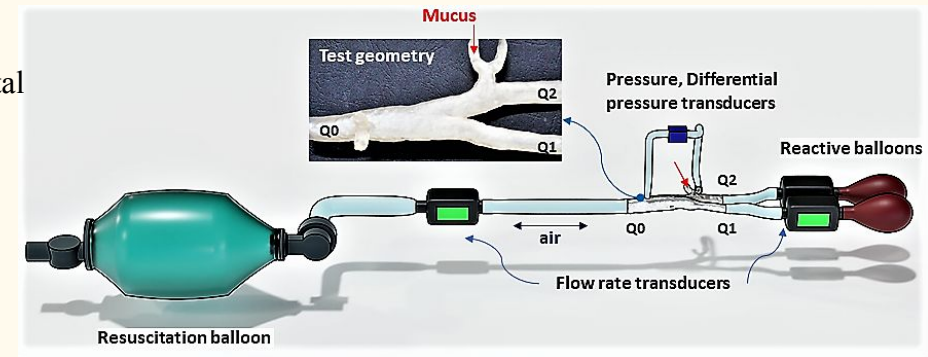
**UPB REOROM
Laboratory
Bucharest
Corneliu Balan**



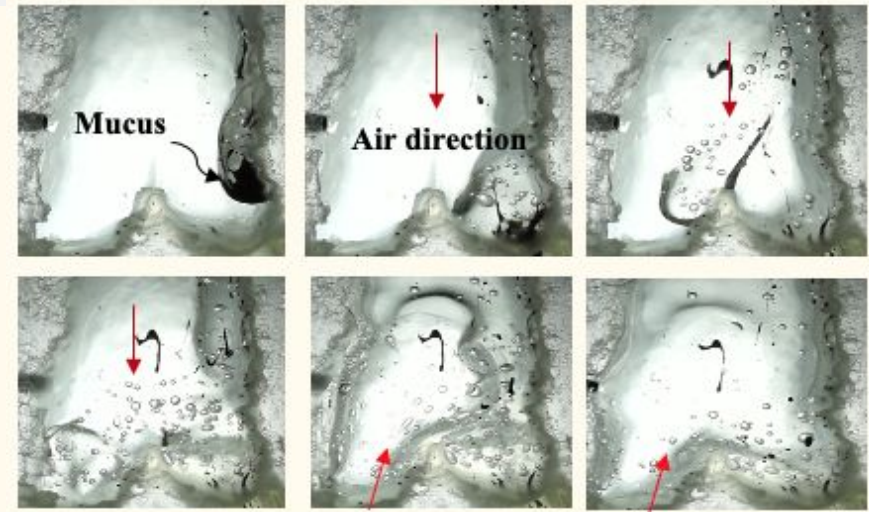
From CT scan to 3D model: step-by-step

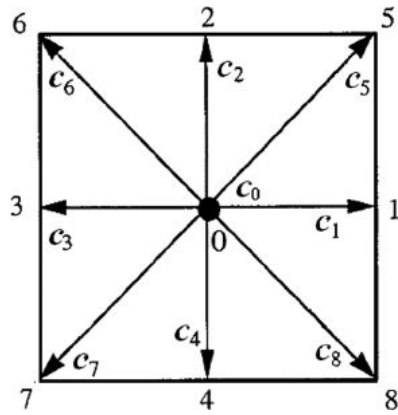
1. Final model from 3DSlicer;
2. The trachea model in Blender interface;
3. Removed unwanted segments;
4. Final solid 3D architecture of the trachea and main bronchi (3D printing);
6. 3D geometry imported in ANSYS Fluent & Moebius;
7. Steady/unsteady simulations;
8. Steady/unsteady path-lines

Experimental setup

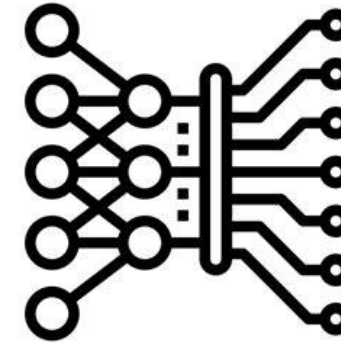


Direct visualization of air-mucus flow in the tracheal bifurcation





Pruning the simulation graph



Requests:

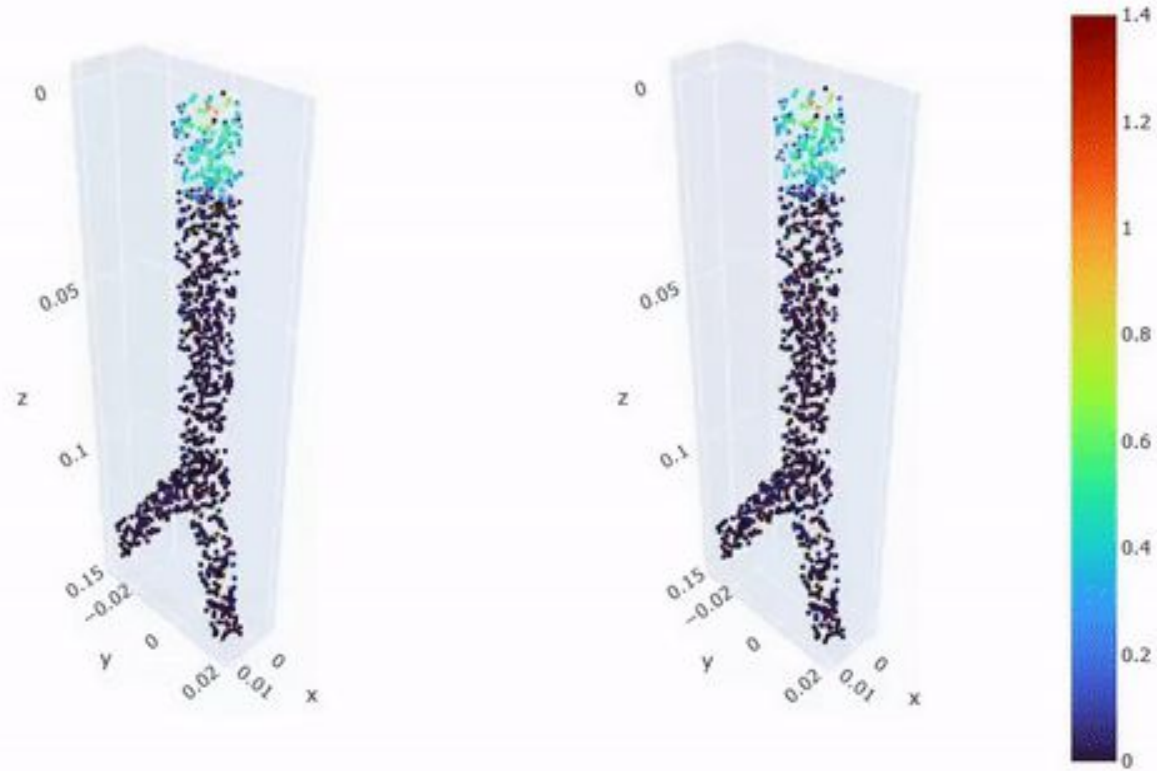
- Isotropy \Rightarrow adjacency must be dense enough
- Steady-state solution \Rightarrow sufficient for the purpose
or
- Propagator \Rightarrow general method for time dependence
- Causality: flow from inlet \rightarrow outlet + irreversibility
- Material properties (relative concentrations) + injection rate as controllable parameters

MeshGraphNet suffers from low resolution as “sensing” confinement requires too many nodes

Propagator mode from the original paper is unneeded (at least for pure-air flow)

One step prediction visualized

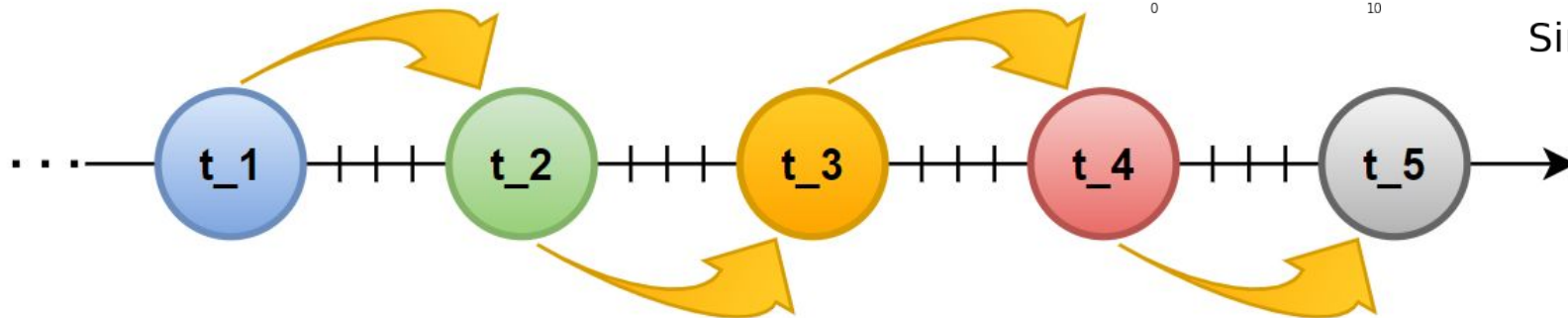
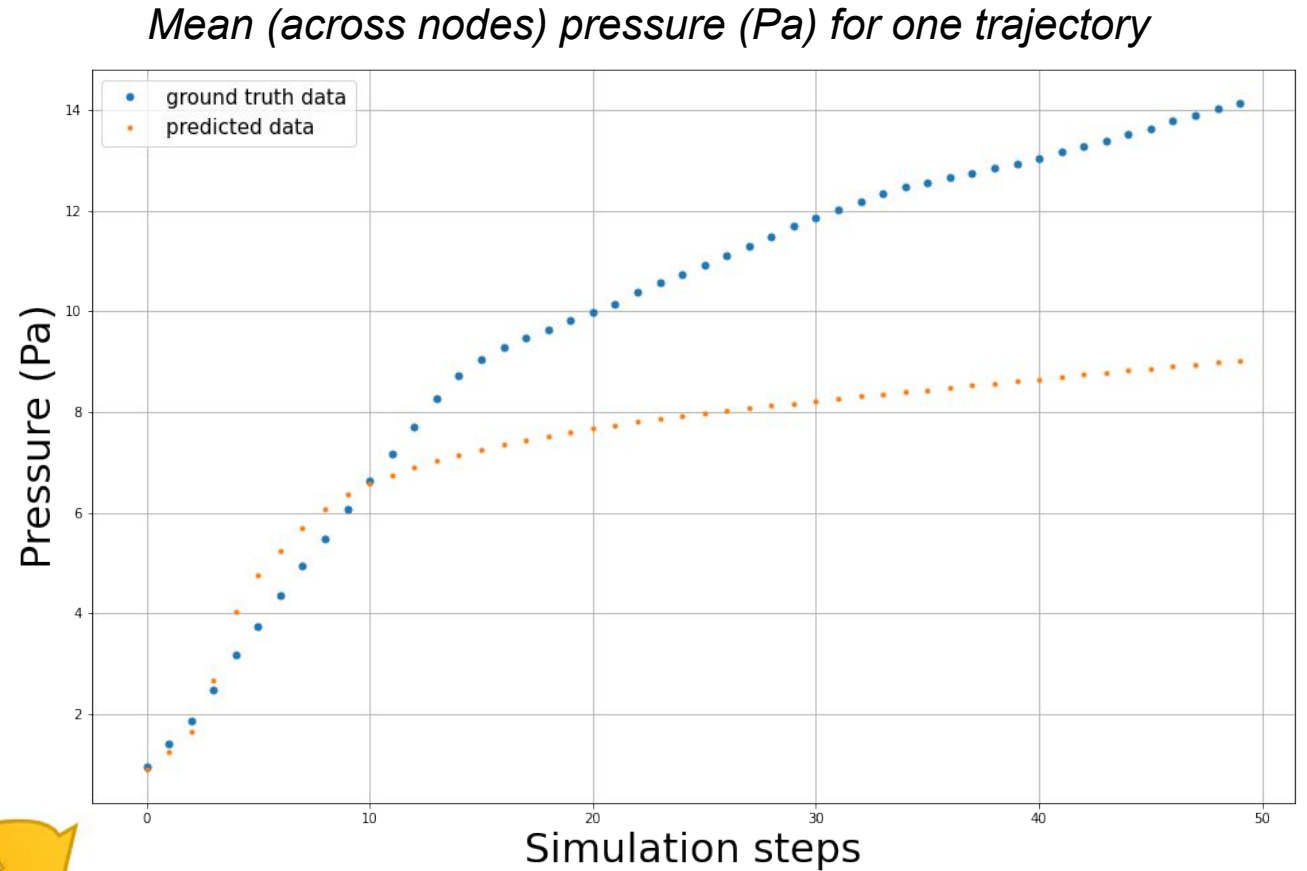
Evolution of velocity module: prediction vs ground truth



Autoregressive test

The model fails in autoregressive mode
It accumulates errors and the prediction diverges! Reasons:

- mass/momentum leakage
- non equivariant (SE3 group)



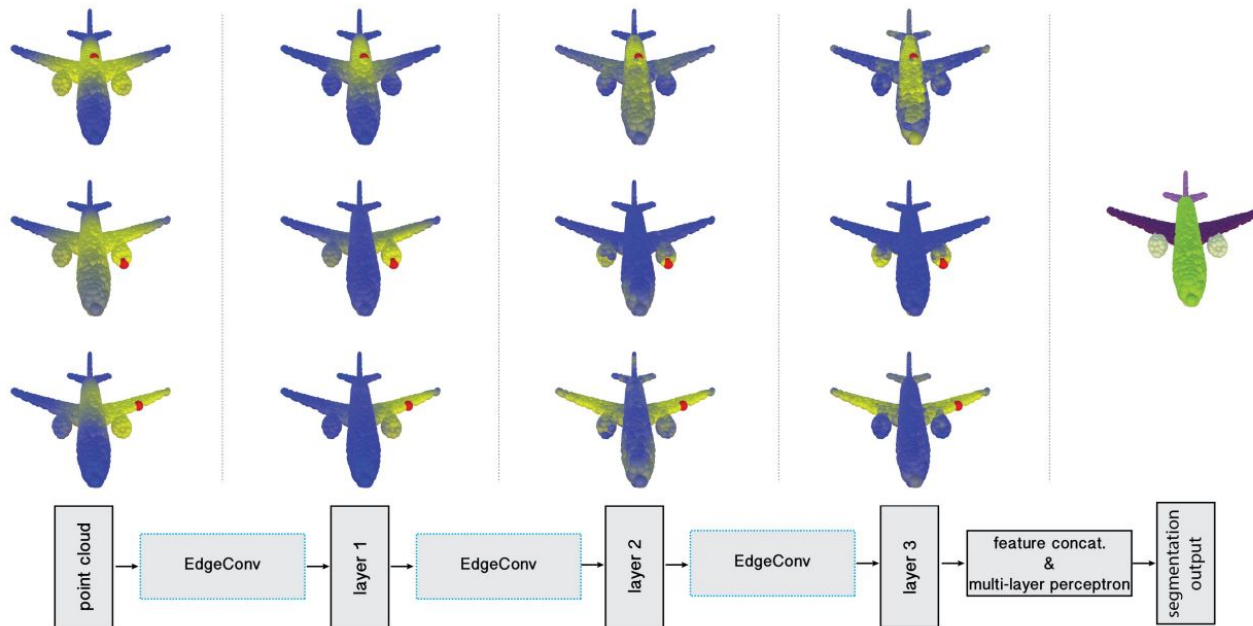
Steady state prediction

Goal: direct prediction of steady-state flow fields given the geometry

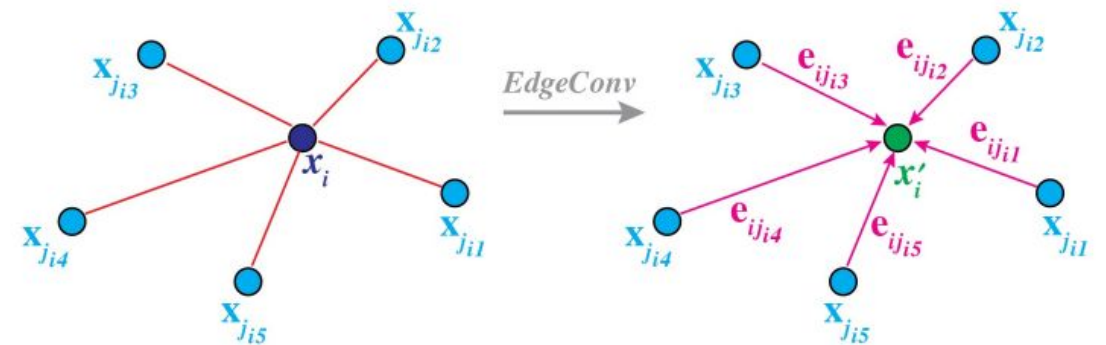
How: develop a model which extracts geometrical features (e.g. spatial coordinates) and uses them to predict physical features (e.g. P,V)

A **different** architecture is needed: DGCNN (Dynamic-Graph CNN)

Used for classification/part segmentation on point clouds



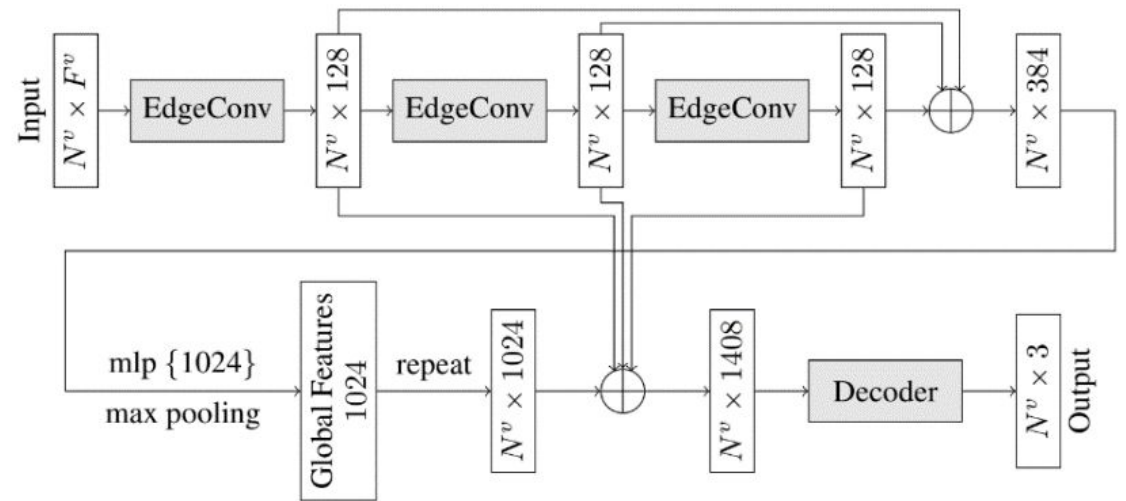
DGCNN layer is called EdgeConv



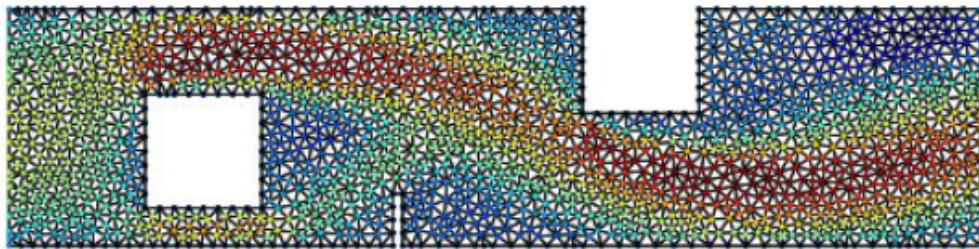
Wang et al. arXiv 2018

Regression task on 2D domains already attempted:

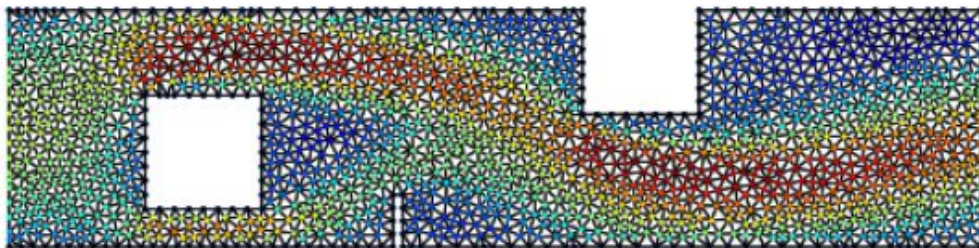
E.g. Harsch et al. ICLR 2021, used **DGCNN** on a dataset composed of 2D channel flows with random objects in them, and one dataset of airfoils embedded in a mesh



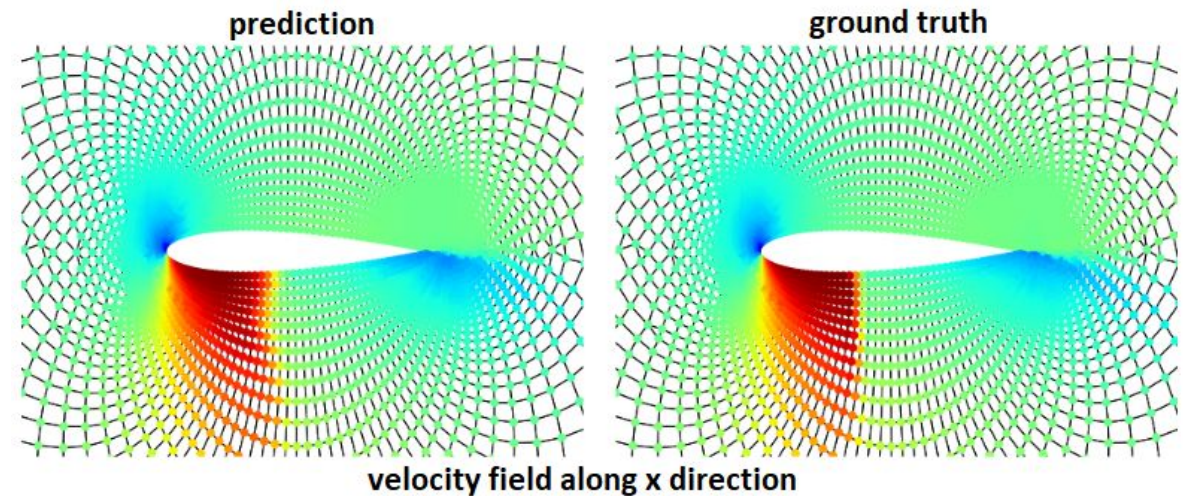
Prediction



Ground truth



velocity field along x direction



velocity field along x direction

xAI to diagnose

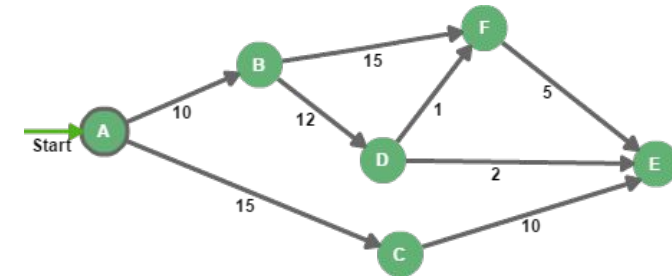
How a doctor decides:

- Direct Diagnosis
 - observe and detect the important blockages
- Diagnosis by Exclusion
 - exclude any other diseases and formulate a diagnosis

The bottom-up approach:

- Why flow distributes unequally? Why a certain region is un-ventilated ?
- Regional plugs along paths: map out the complex landscape for ventilation
- Given the regional fluxes, is air path quantifiable on end-points and in tissues ?
- Provide the analogue of Dijkstra's method, backtrack effective and/or failing ventilatory paths

Which xAI best fits (saliency, TRACIN, occlusion, topological, ...) ?



Dealing with large graphs

Data production:

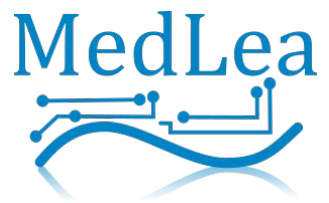
1. 3D simulations for small bricks
2. skeletonization to compress information: velocity, pressure, MIS
3. exploit self-similarity
4. all relevant quantities become scalars (equivariance is built-in)



AI prediction
xAI diagnosis



1. de-skeletonize for local details
2. calibrate / validate
3. re-model



www.medlea-tech.com

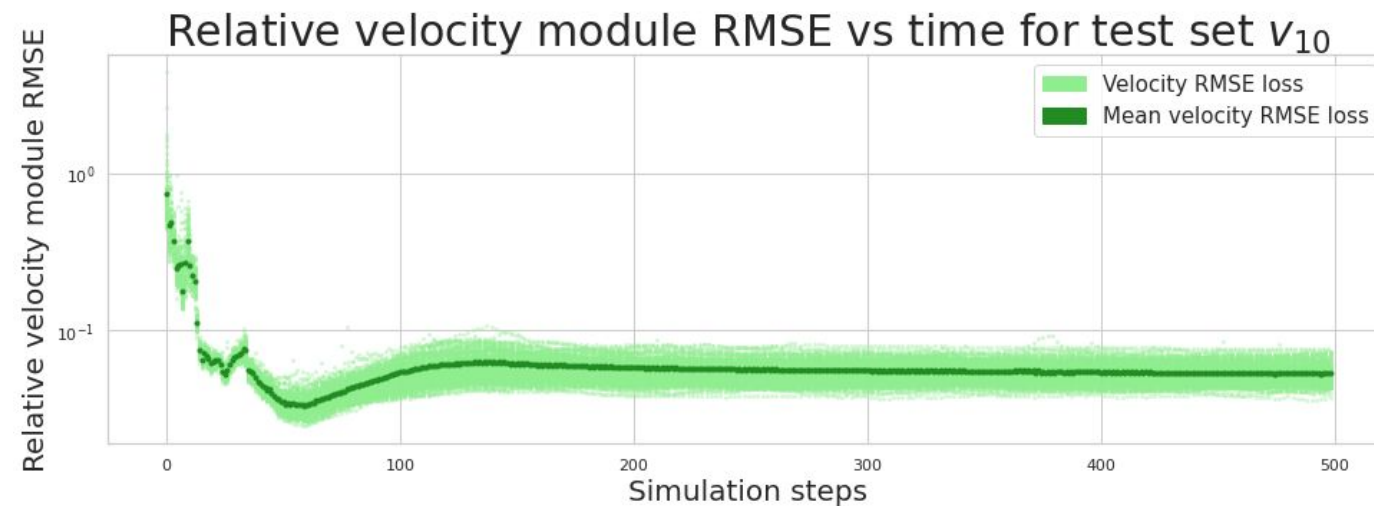
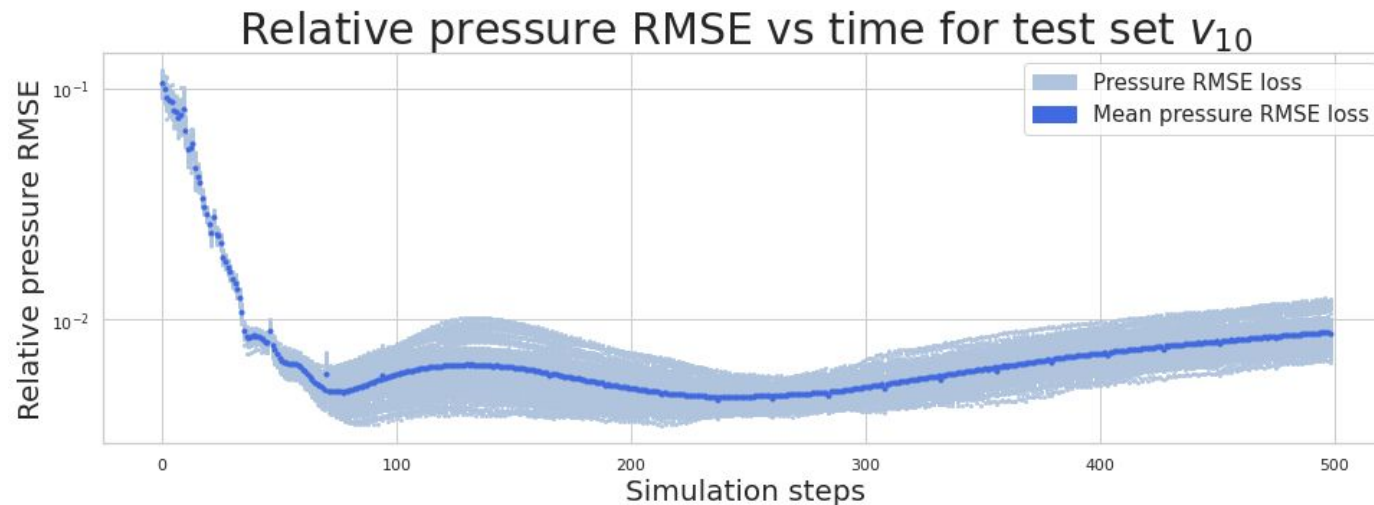
Thank you
... and ...
we are hiring!

Generalization test

Generalization test on different inlet velocities

- Held out test velocities: v_1 , v_{10}
- Model is trained on simulations in groups from v_2 to v_9

On the right: plots of the mean (across nodes) relative root mean-squared error (**RMSE**) for pressure and velocity module, for the 100 trajectories of one test set. Darker color represent the mean across the 100 trajectories.



We are interested in 3D domains

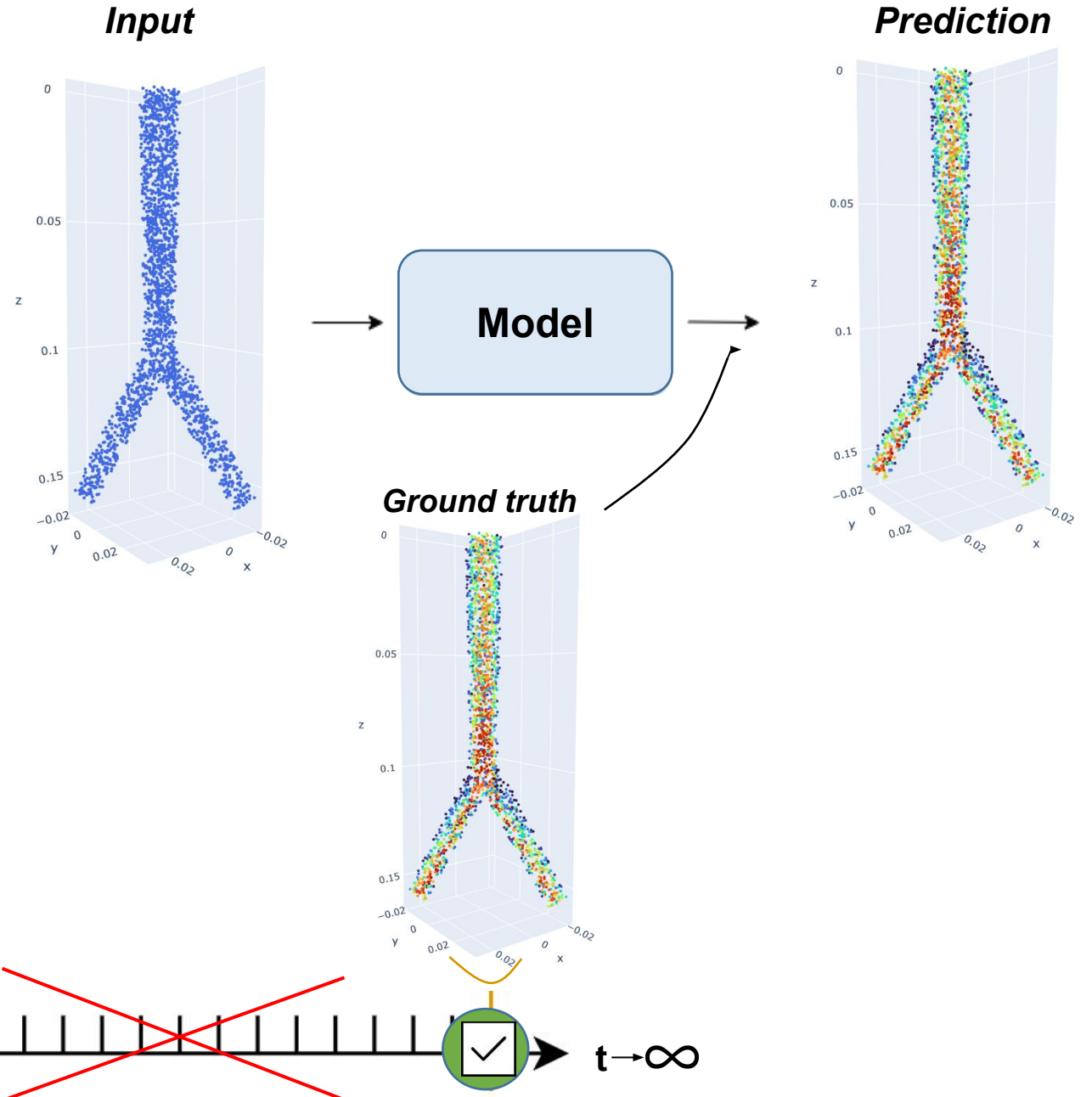
Task identification

Steady state predictor

1. *Input state*: sampled point cloud resembling the underlying geometry
2. *Output state*: pressure and velocity fields and stress tensor components measured in the steady state

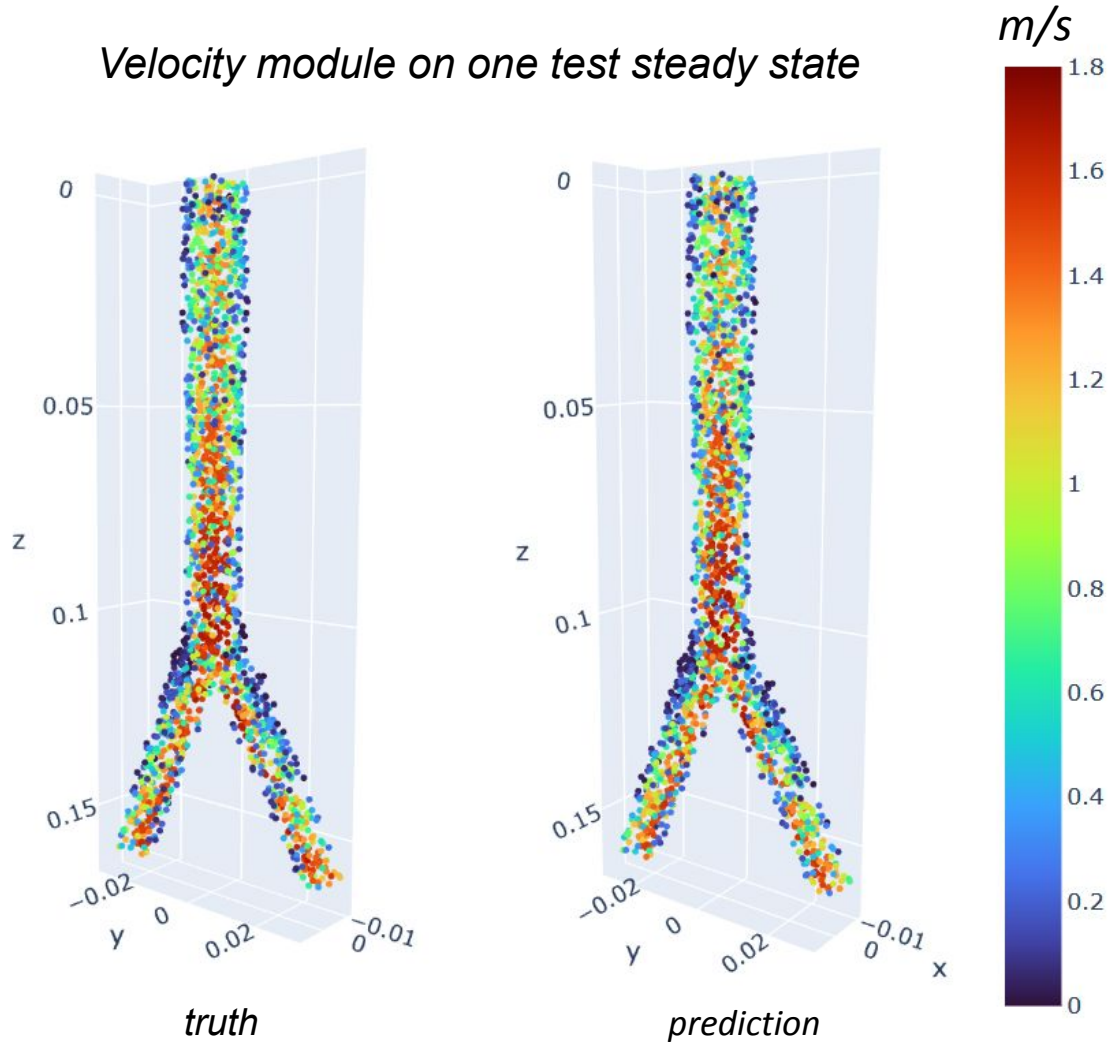
Dataset production

1. 2000 simulations with fixed inlet velocity
2. Uniform sampling of $n=2000$ points
3. Physical features are extracted only once, when the system has reached the steady state: **1 simulation = 1 data point, time is no longer relevant**

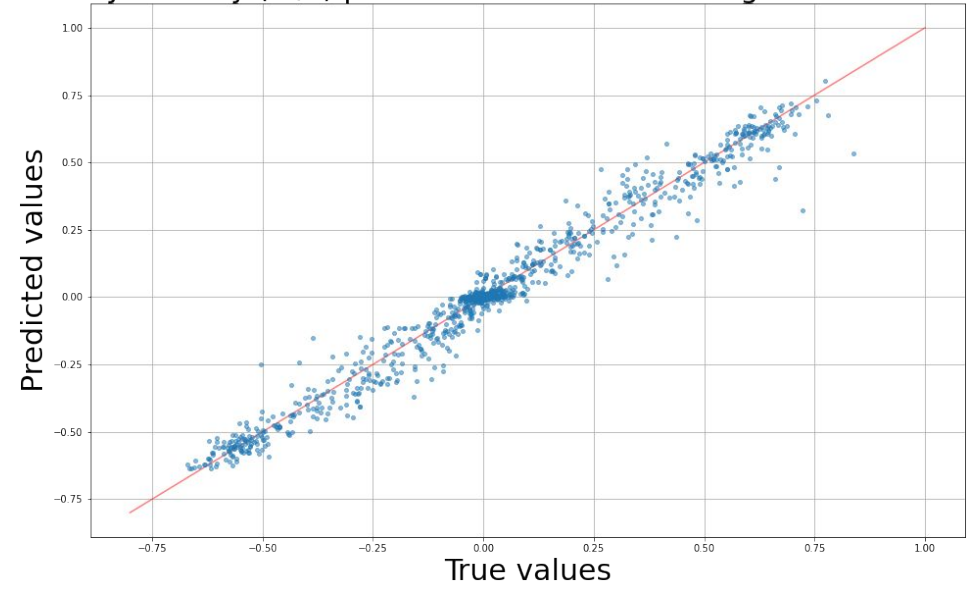


Preliminary results

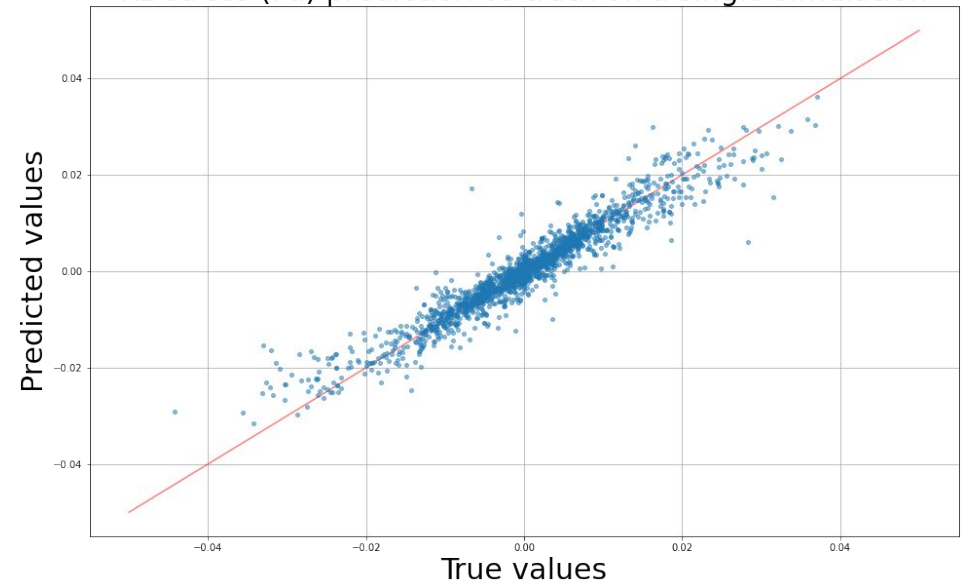
Velocity module on one test steady state



y velocity (m/s) prediction vs truth on a single simulation



xz stress (Pa) prediction vs truth on a single simulation



The SimInhale benchmark (from Cost action MP1404)



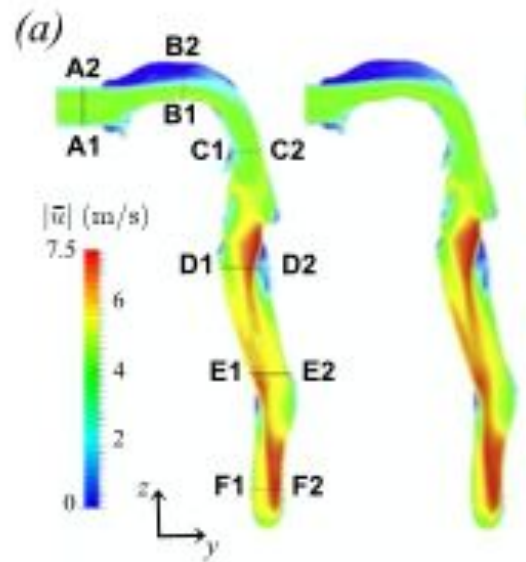
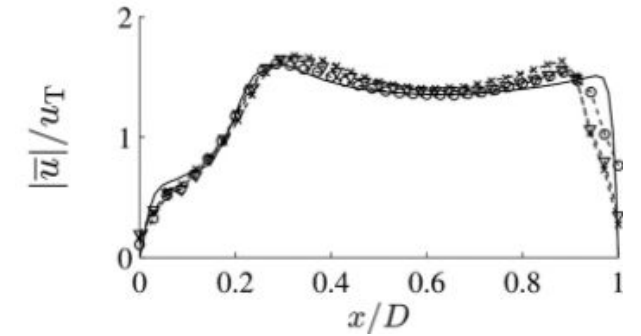
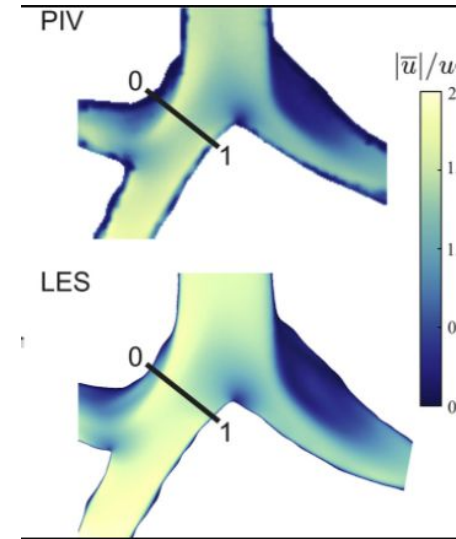
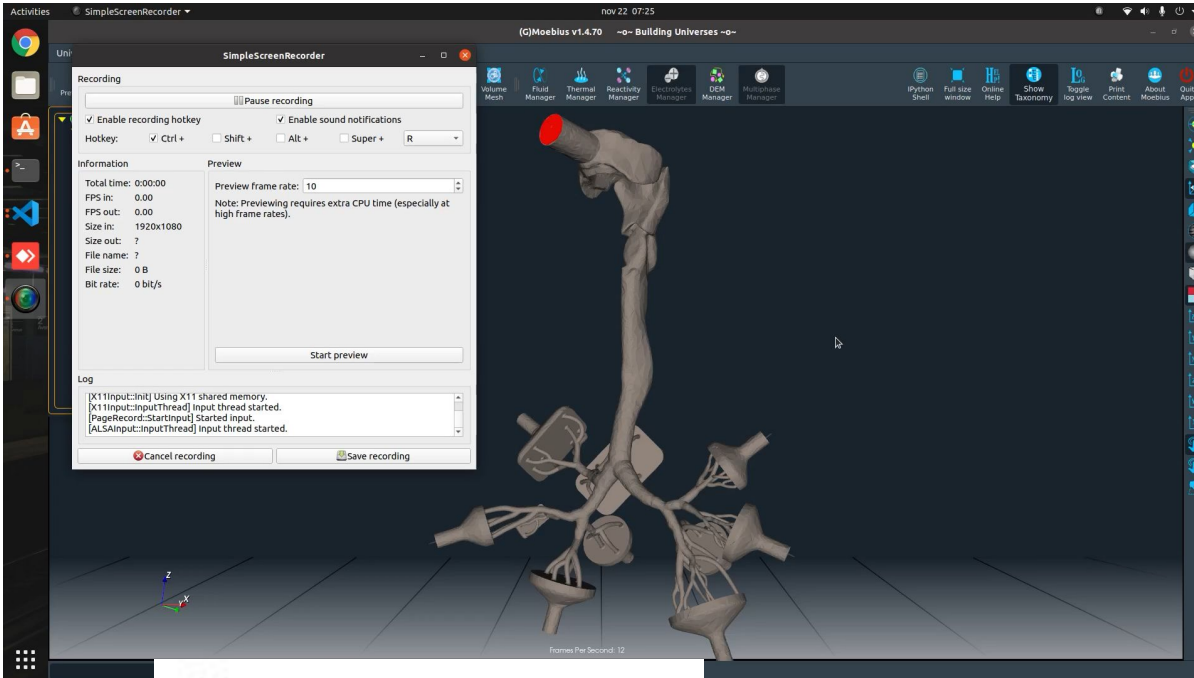
Contents lists available at ScienceDirect

European Journal of Pharmaceutical Sciences

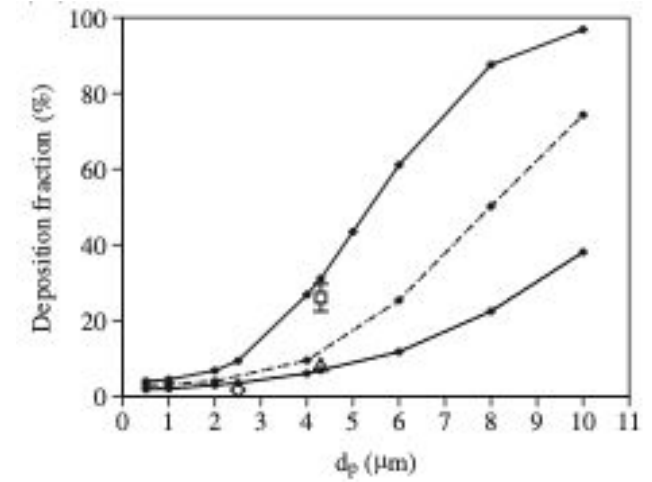
journal homepage: www.elsevier.com/locate/ejps

Regional aerosol deposition in the human airways: The SimInhale benchmark case and a critical assessment of *in silico* methods

P. Koullapis^a, S.C. Kassinos^a, J. Muela^b, C. Perez-Segarra^b, J. Rigola^b, O. Lehmkuhl^c, Y. Cui^d, M. Sommerfeld^e, J. Elcner^f, M. Jicha^f, I. Saveljic^g, N. Filipovic^g, F. Lizal^f, L. Nicolaou^{h,*}



Fully reconstructed airways to 4th generation
Benchmark for fluid mechanics and PIV data
Focus on particle deposition

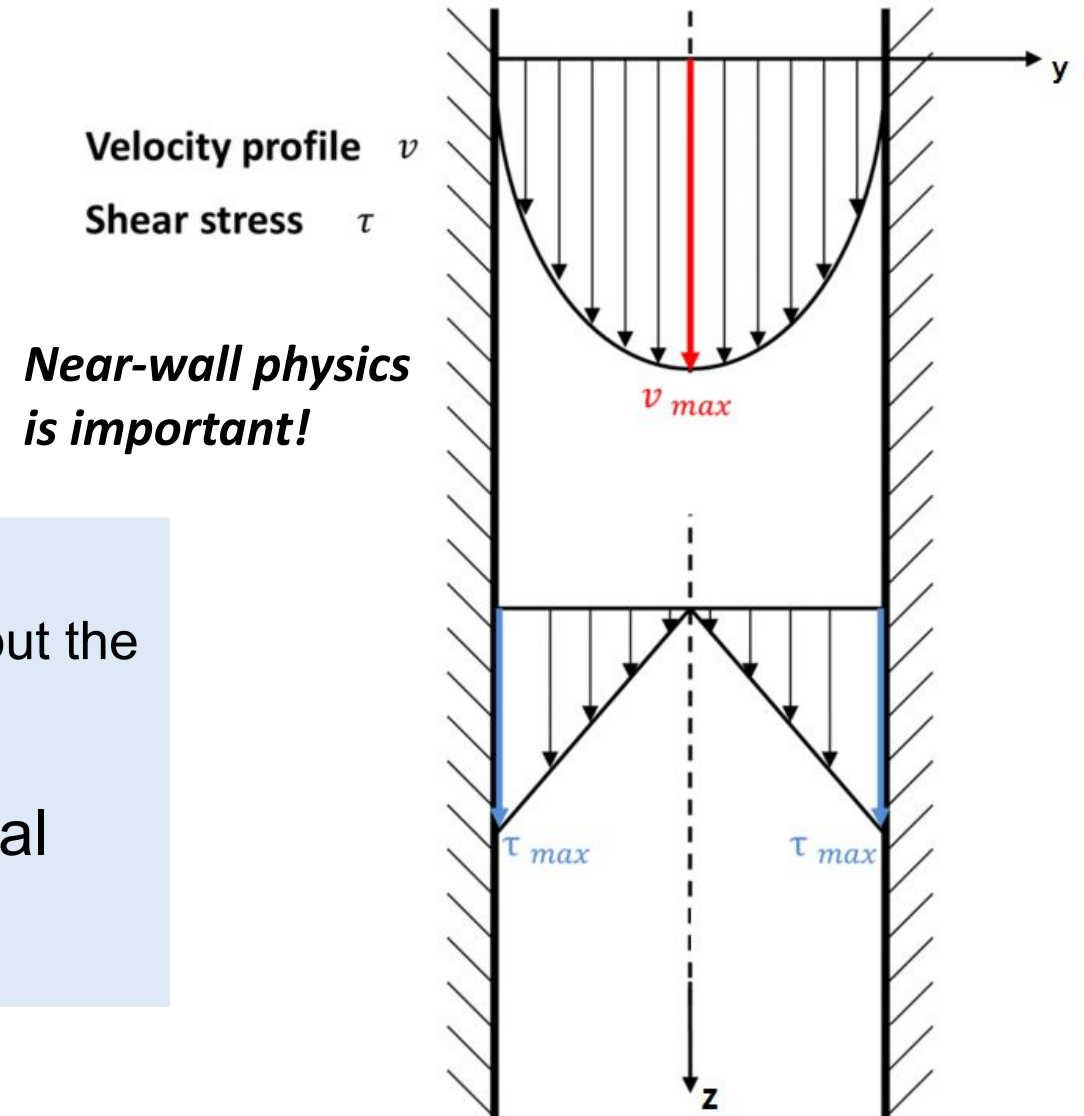


Adding new features: stress components

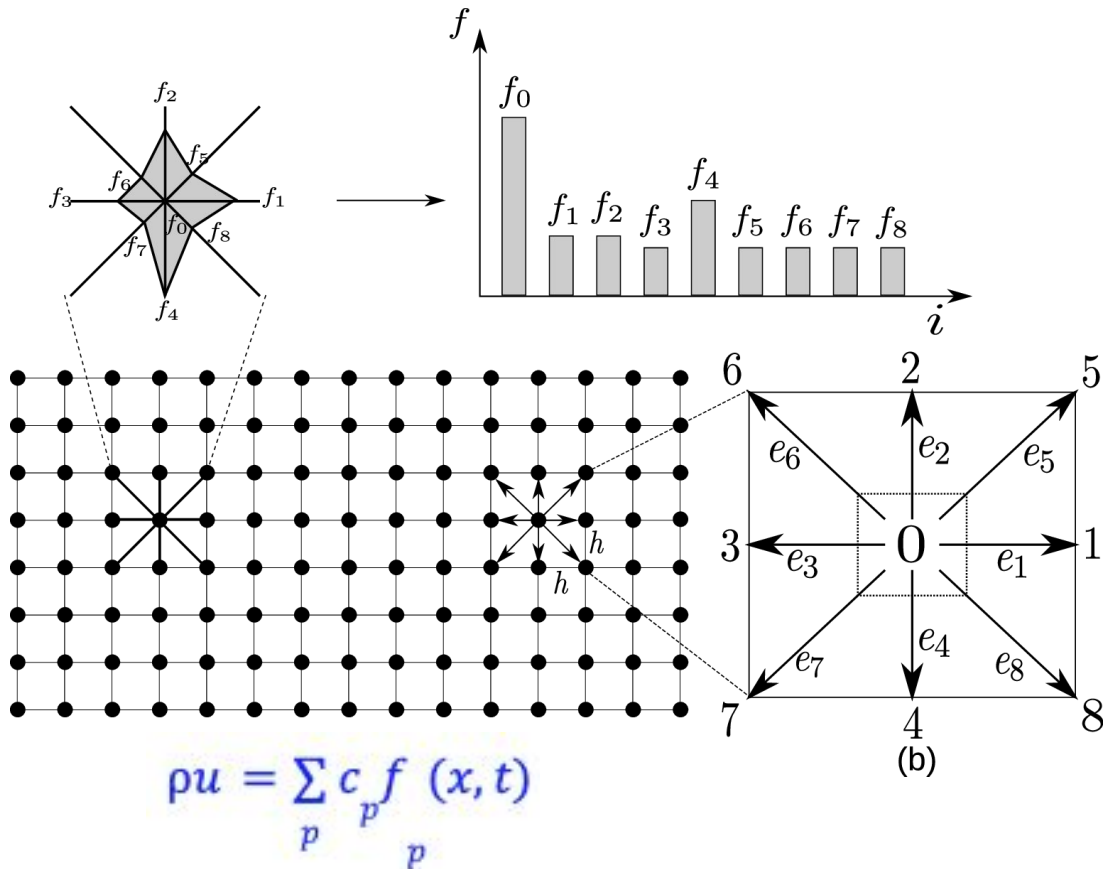
In the last few months, we also added the stress tensor components, to better inform the model about velocity gradients.

The model is capable of managing additional features without degrading pressure and velocities prediction, but the autoregressive goal still requires a lot of work.

We decided to change our task from a physical propagator to a **steady state predictor**



Simulation details



$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p + \mathbf{F} + \frac{\mu}{\rho} \nabla^2 \mathbf{u}$$

One control parameter:
*Reynolds number = diameter*velocity/viscosity*

Lattice Boltzmann Method (kinetic approach)

Nodes on a dense graph with regular adjacency

High-order Isotropy

Collisions + message passing at every micro-step

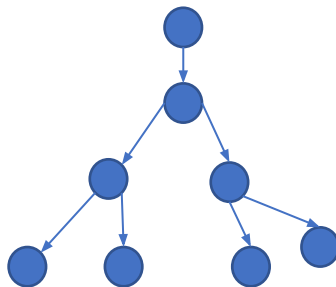
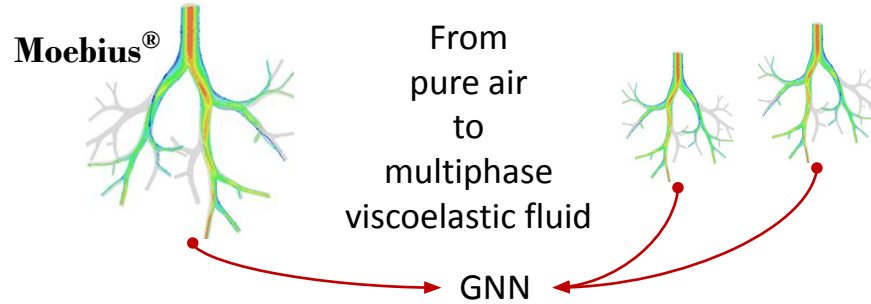
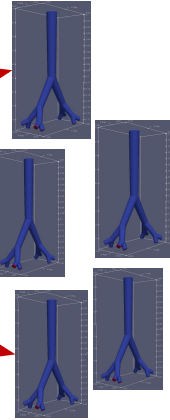
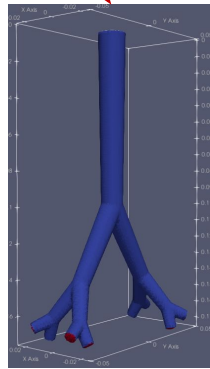
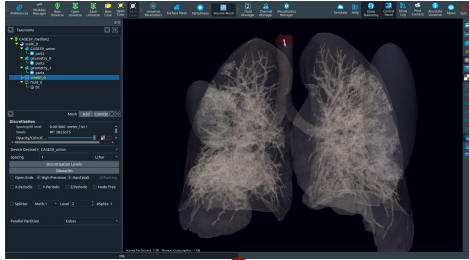
Same approach for hollow airways & porous tissues

$$f_p(x + hc_p, t + h) = \frac{1}{\tau} f_p^{eq} + \left(1 - \frac{1}{\tau}\right) f_p + F_p$$

Dissipative and irreversible dynamics (obeying MaxEnt theorem)

Field-particle duality encoded: particle tracking to determine the swarm of pathlines

Airflows



Confined, stationary flow in complex pipes and air-mucus flow

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p + \mathbf{F} + \frac{\mu}{\rho} \nabla^2 \mathbf{u}$$

Pulsatile period \gg viscous timescale \Rightarrow final state vs boundary condition

1:1 mapping between injection rate and flow pattern

Air-mucus creeping dynamics has a slow evolution

Pulsatile dynamics as a sequence of stationary states (adiabatic process)

GNN

How do we work on graph data?

Graph neural networks

- Used on unstructured data: molecules, social networks ecc.
- Based on **message passing**, a generalization of convolution
- Suitable architecture to leverage physical inductive biases:
 - Local interactions
 - Superposition principle

