

Progress on two-loop integrals for top-pair production plus a W boson



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Theory and Phenomenology
of Fundamental Interactions
UNIVERSITY AND INFN · BOLOGNA

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Motivation

High luminosity LHC plan



Experimental precision for HL-LHC of $\mathcal{O}(1\%)$ for many observables

Theoretical predictions at higher orders are required to match experimental precision. Typically: at least NNLO QCD

Main bottleneck: 2-loop 5-point scattering amplitudes

Cross sections for $h_1 h_2 \longrightarrow f$:

$$d\sigma_{h_1 h_2 \rightarrow f} = \sum_{i,j=q,\bar{q},g} \int \int dx_1 dx_2 \mathcal{F}_{i/h_1}(x_1, \mu^2) \mathcal{F}_{j/h_2}(x_2, \mu^2) d\hat{\sigma}_{ij \rightarrow f}(\vec{s}, \mu^2)$$

Partonic cross section:

$$d\hat{\sigma}_{ij \rightarrow f} \sim \int d\Phi |\mathcal{A}|^2$$

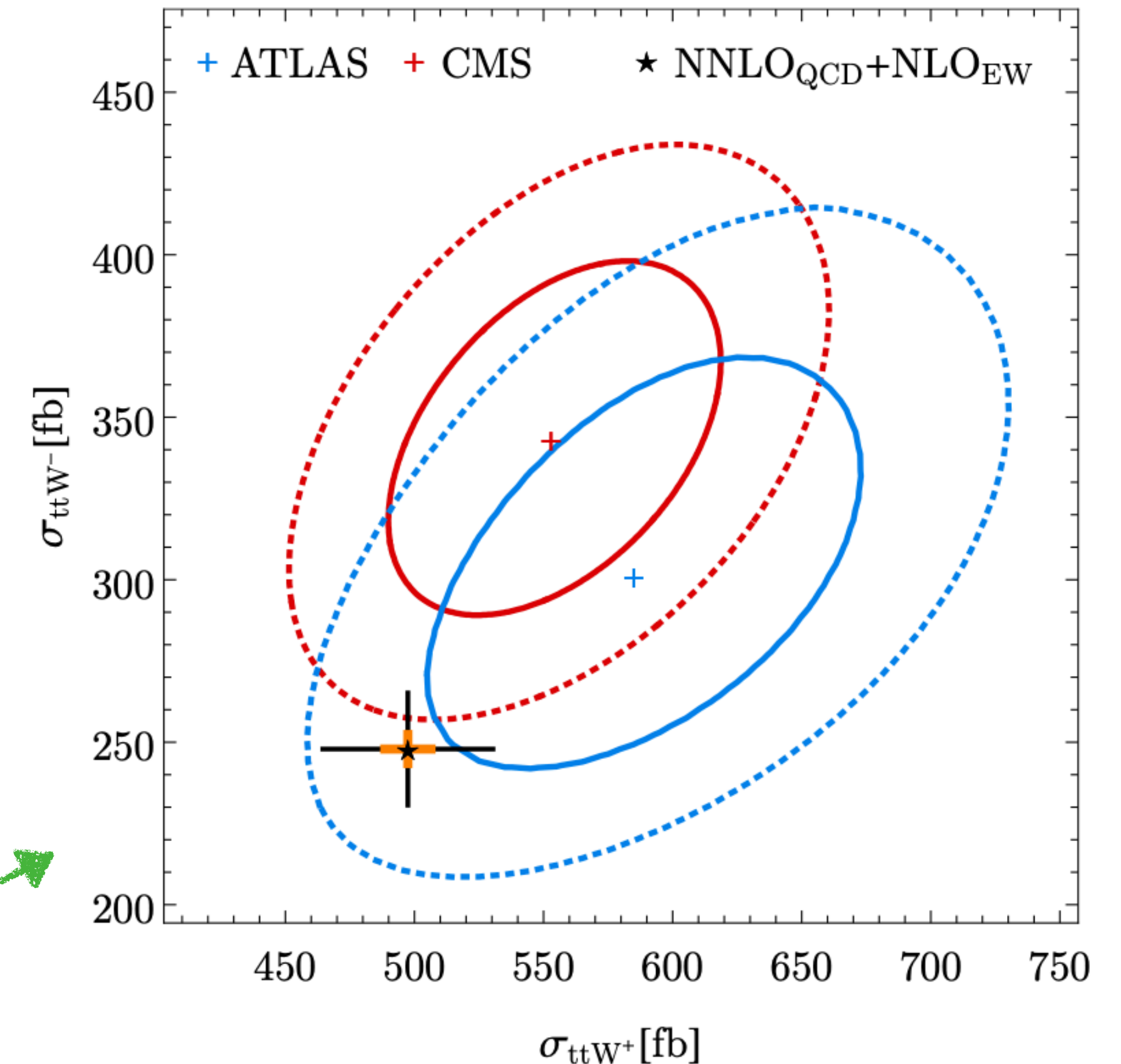
Amplitude:

$$\mathcal{A} \sim \sum_i F_i(\vec{s}; \epsilon) G_i(\vec{s}; \epsilon)$$

Feynman Integrals

Motivation

- $t\bar{t}W$ production is relevant for BSM searches and constitutes a significant background for $t\bar{t}H$ and $t\bar{t}t\bar{t}$ production in Standard Model
- Theoretical predictions systematically underestimate measured rates [ATLAS 2024 and CMS 2023]. Currently within uncertainties, but experimental precision is set to increase
- NNLO: 2-loop amplitude approximated with soft-W and massification [Buonocore et al. 2023]
- Exact 2-loop amplitude is needed to remove uncertainty of approximation



What's the challenge?

- ⊙ Complexity originates from:
 - Massive internal propagators
 - Five external legs, two different external scales
- ⊙ Analytic complexity
 - Functions beyond the polylogarithmic case
- ⊙ Algebraic complexity
 - State of the art calculations: usually localised in the amplitude part of the calculation
 - Here: large expressions already in the differential equations for the integrals

Status of related calculations

- $t\bar{t}$: complete NNLO QCD corrections [Czakon et al. 2012, 2013 and 2016; Catani et al. 2019 and 2020]
- $t\bar{t}j$: NLO QCD corrections up to $\mathcal{O}(\varepsilon^2)$ [Badger et al. 2022], two-loop integrals in the leading colour approximation [Badger et al. 2023 and 2024; Becchetti et al. 2025] and numerical evaluation of the amplitude [Badger et al. 2024]
- $t\bar{t}H$: NLO QCD corrections up to $\mathcal{O}(\varepsilon^2)$ [Buccioni et al. 2024]. Numerical results for a set of two-loop Feynman integrals [Febres Cordero et al. 2024] and two-loop N_f part of the quark-initiated scattering amplitudes [Agarwal et al. 2024]
- $t\bar{t}Z$: NLO QCD corrections [Lazopoulos et al. 2008, Kardos et al. 2012], NLO QCD and EW corrections [Frixione et al. 2015]

Kinematics

$$\bar{t}(p_1) + t(p_2) + \bar{d}(p_3) + W(p_4) + u(p_5) \longrightarrow 0$$

- Momentum conservation:

$$p_1 + p_2 + p_3 + p_4 + p_5 = 0$$

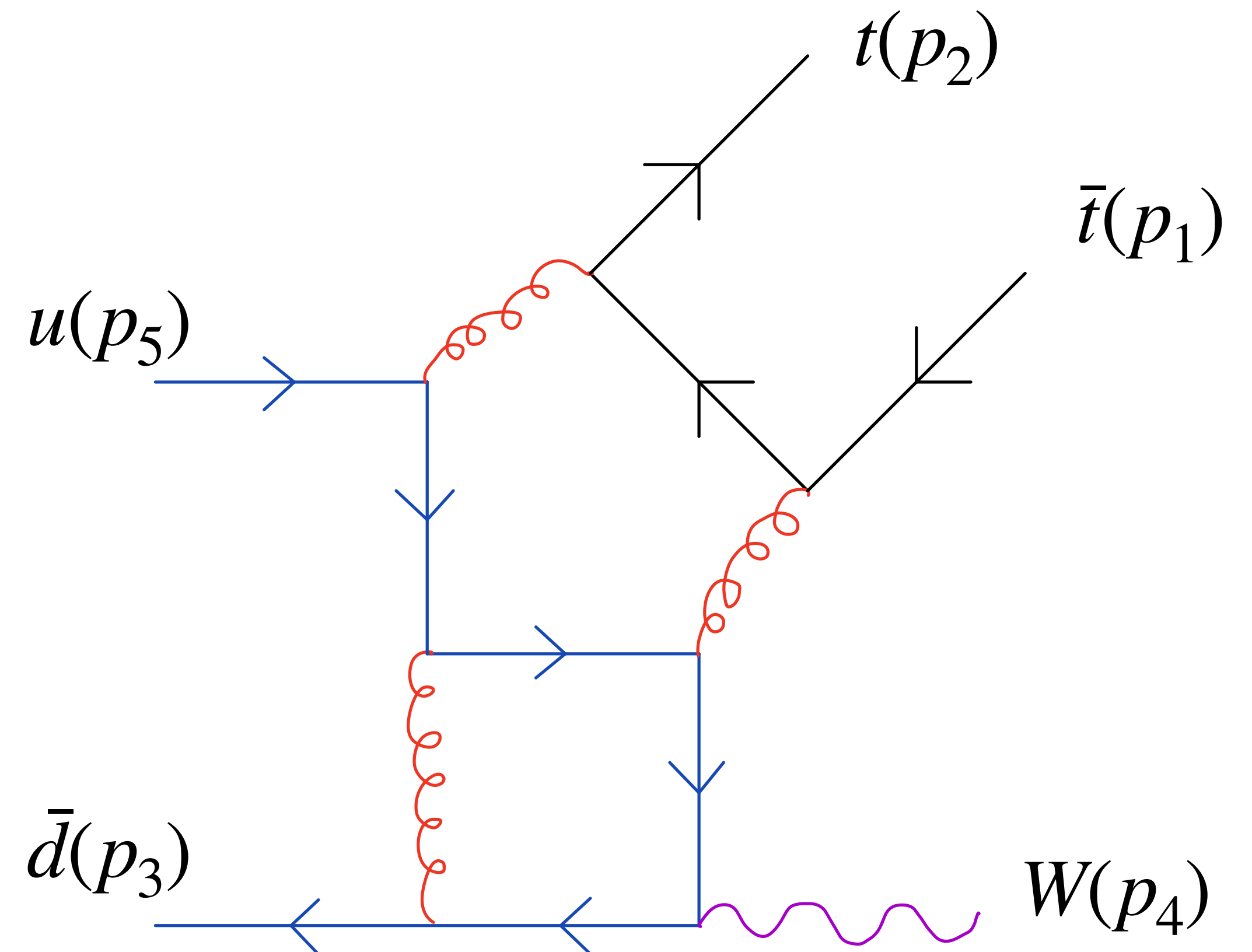
- $p_1^2 = p_2^2 = m_t^2$, $p_3^2 = p_5^2 = 0$, $p_4^2 = m_W^2$

- 7 Invariants:

$$\vec{x} := \{s_{12}, s_{23}, s_{34}, s_{45}, s_{15}, m_t^2, m_W^2\}, \text{ with}$$

$$s_{ij} = (p_i + p_j)^2$$

- Dimensional regularisation: $d = 4 - 2\varepsilon$



Integral families

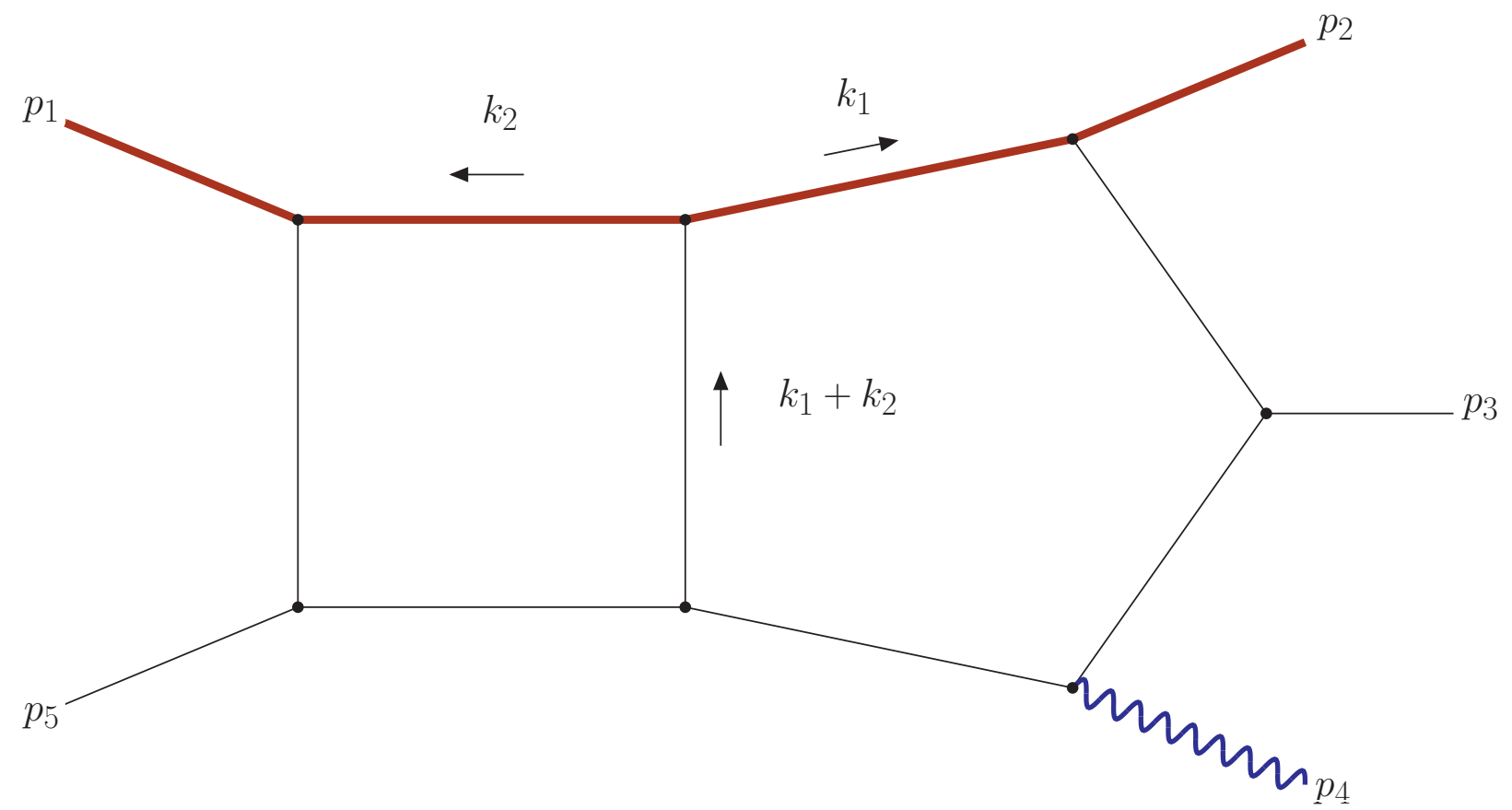
$$G_{a_1, \dots, a_{11}} = \int d^d k_1 d^d k_2 \frac{1}{D_1^{a_1} \dots D_{11}^{a_{11}}}, \quad (a_1, \dots, a_{11}) \in \mathbb{Z}^{11}$$

Propagators of Feynman integrals

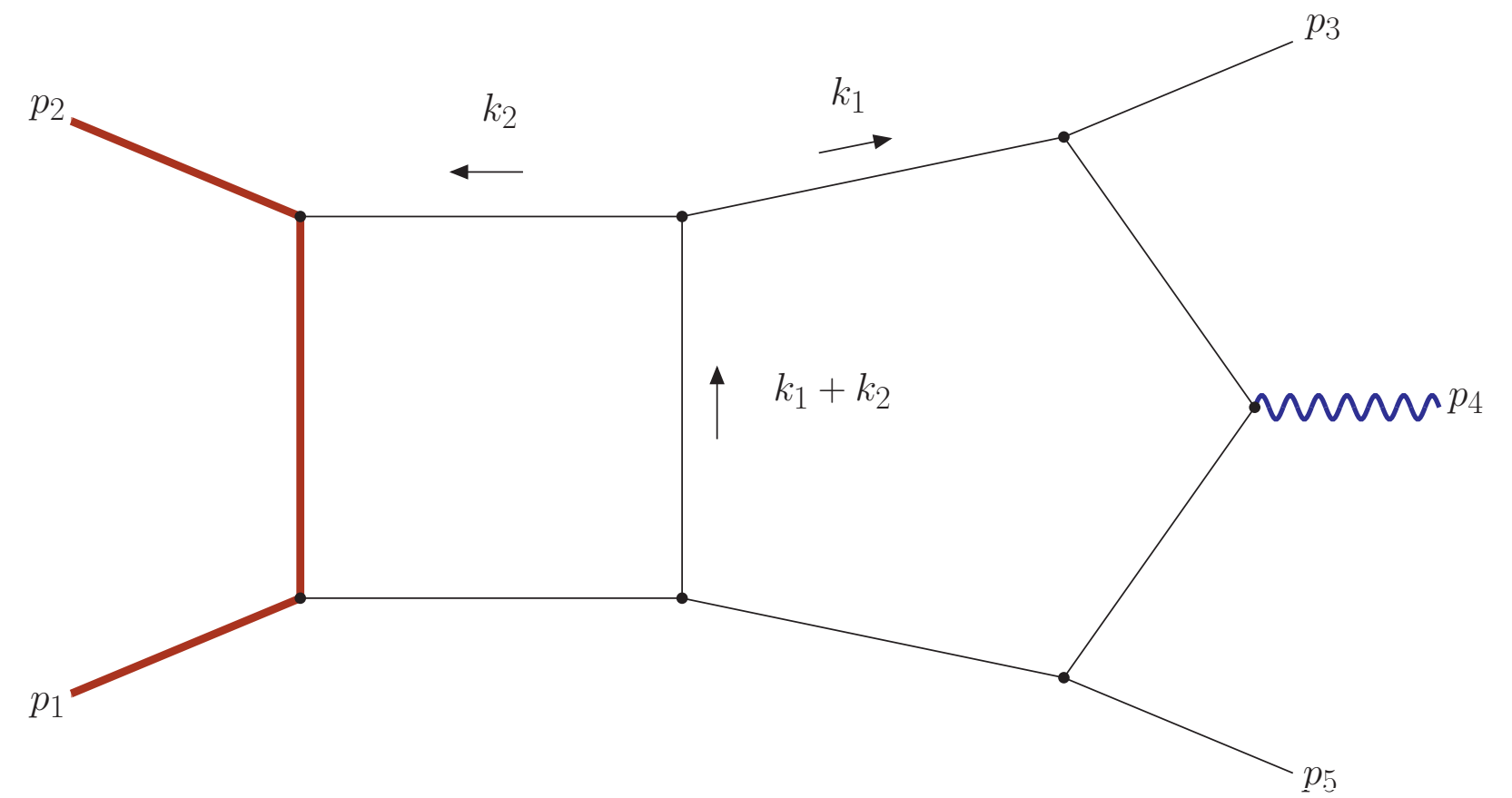
- Sectors: same non-negative exponents
- Top sector: maximum number of non-negative exponents
- Amplitude calculations: express $k_i \cdot p_j$ and $k_i \cdot k_j$ in terms of propagators

\implies Beyond one-loop we need irreducible scalar products (ISPs). Here: 3 ISPs

$t\bar{t}W$ integral families

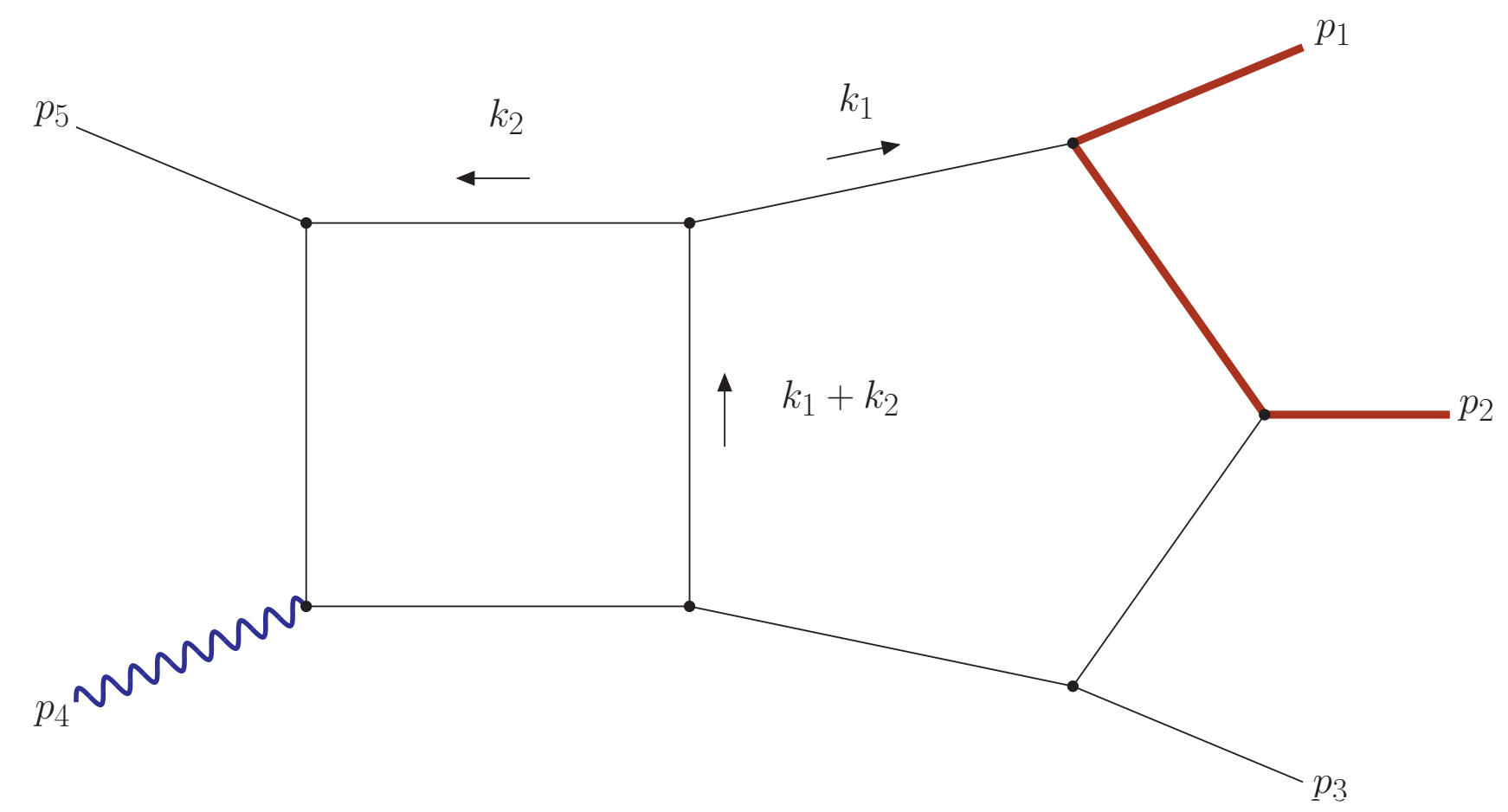


Family F_1 : 141 MIs



Family F_2 : 122 MIs

Family F_3 : 131 MIs



IBPs and reduction to Master Integrals

- Feynman integrals satisfy linear relations: integration by part identities (IBPs) [Chetyrkin, Tkachov '81]

$$0 = \int d^d k_1 d^d k_2 \frac{\partial}{\partial k_l^\mu} \frac{v^\mu}{D_1^{a_1} \dots D_{11}^{a_{11}}}, \quad v^\mu \in \{k_j^\mu, p_j^\mu\}$$

- Reduction to master integrals

$$\sum_{\vec{a}_k} c_{\vec{a}_k}(\vec{x}; \varepsilon) G_{\vec{a}_k}(\vec{x}; \varepsilon) = 0 \implies G_{\vec{a}}(\vec{x}; \varepsilon) = \sum_j c_{\vec{a},j}(\vec{x}; \varepsilon) I_j(\vec{x}; \varepsilon)$$

Master Integrals
(MIs) $\vec{I}(\vec{x})$

- Laporta algorithm: IBPs generated for some seeding [Laporta 2000]
- Finite Fields techniques [von Manteuffel, Schabinger 2014; Peraro 2016] to tackle algebraic complexity
- NeatIBP [Wu et al. 2023] and FiniteFlow [Peraro 2019] to generate and solve an optimised system of IBPs

Method of differential equations

[Kotikov '91; Bern, Dixon, Kosower '94; Gehrmann, Remiddi 2000]

- Using IBPs we can construct linear differential equations (DEs) for the MIs

$$\forall \xi \in \vec{x} : \quad \partial_{\xi} I_i(\vec{x}; \varepsilon) = \sum_{\vec{a}} c_{i,\vec{a}}(\vec{x}; \varepsilon) G_{\vec{a}}(\vec{x}; \varepsilon)$$

$$\implies \partial_{\xi} \vec{I}(\vec{x}; \varepsilon) = B_{\xi}(\vec{x}; \varepsilon) \cdot \vec{I}(\vec{x}; \varepsilon)$$

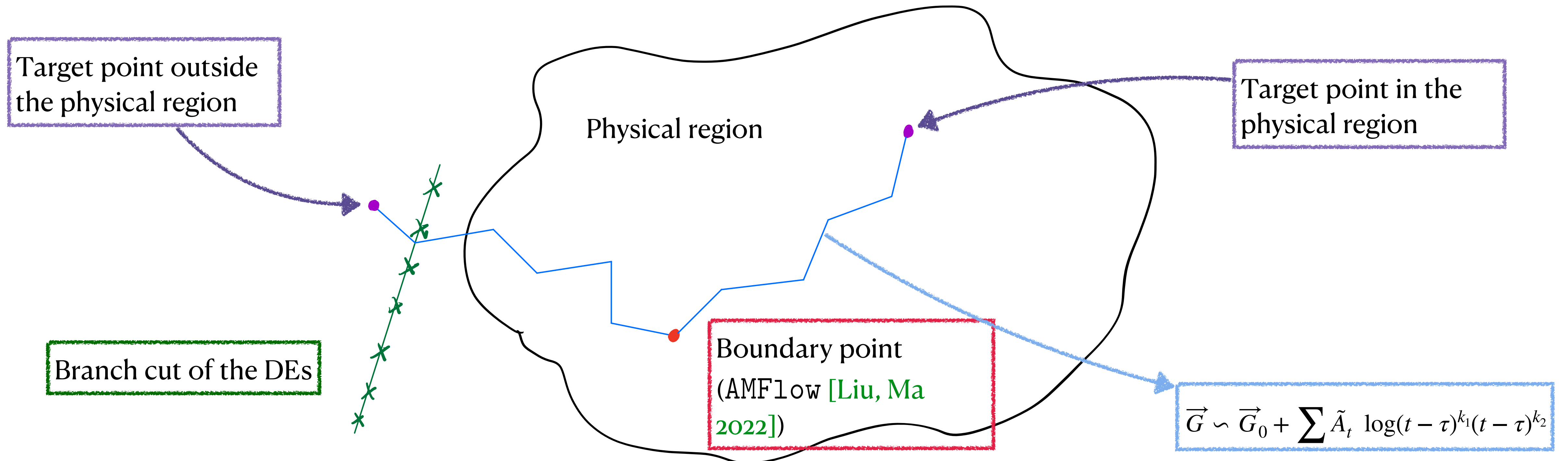
IBP reduction

- Many strategies to solve the differential equation. Our choice: semi-numerical approach using `DiffExp` [Hidding 2020]

- Suitable for very general problems
- The implementation supports only rational functions and simple square roots

Semi-numerical evaluation

- Generalised series expansion method [Moriello 2019]: approximate the solution in terms of logs along the integration path



- Work in the physical region: no analytic continuation needed!

What is a good choice of basis of MIs?

● The basis of MIs is not unique. A good choice of basis can greatly simplify the DEs

● [Henn 2014]: DEs in canonical form (no general algorithm)

$$d\vec{I}(\vec{x}; \varepsilon) = \varepsilon d\tilde{A}(\vec{x}) \vec{I}(\vec{x}; \varepsilon)$$

one-forms with at most simple poles

● In the best understood cases the one-forms are logarithmic

$$d\tilde{A}(\vec{x}) = \sum_i a_i d \log W_i(\vec{x})$$

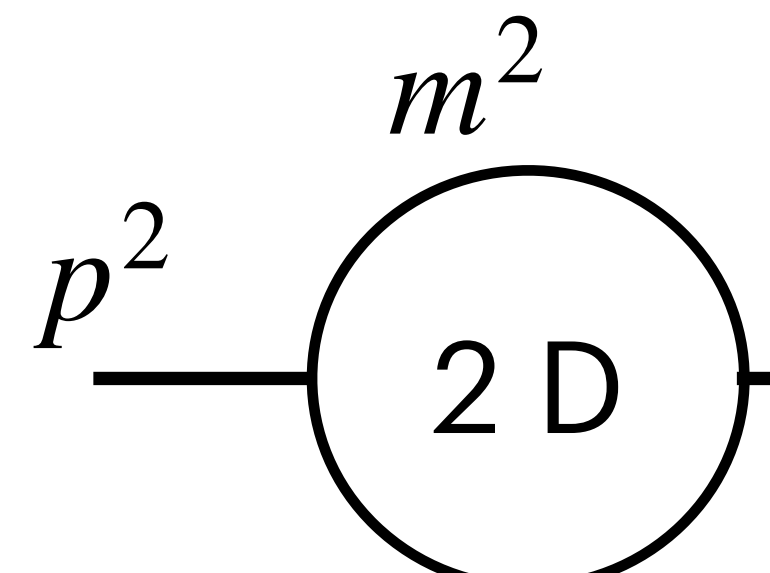
Letters

- ε dependence factorises: solution at each order depends only on previous order
- Full control over linear relations through iterated integrals representation of the solution \implies Construction of a minimal basis of special functions, which simplifies the representation of the amplitude
- Well-established techniques to handle the solution of the DEs

**How do we construct a
canonical basis?**

Dlog-integrands and leading singularities

- Conjecture: integrals with a loop-integrand with at most simple poles and a constant leading singularity are good MIs



A Feynman diagram showing a circular loop with mass m^2 and external momentum p^2 . The loop is labeled "2 D".

$$\propto \int \frac{d\alpha_1 \wedge d\alpha_2}{p^2(\alpha_1\alpha_2 - z)[(1 + \alpha_1)(1 + \alpha_2) - z]}$$

$$= \int \frac{d\alpha_1}{p^2(\alpha_1^2 + \alpha_1 + z)} \left[d \log(\alpha_1\alpha_2 - z) - d \log(1 + \alpha_1 + \alpha_2 + \alpha_1\alpha_2 - z) \right]$$

$$= \frac{1}{p^2\sqrt{1-4z}} \int d \log(\dots) \wedge d \log(\dots)$$

Leading singularity (LS) \rightarrow $\frac{1}{p^2\sqrt{1-4z}}$ $\int d \log(\dots) \wedge d \log(\dots)$ \leftarrow *dlog*-form

$$d \log(z + c) = \frac{dz}{z + c}$$

- Commonly: rational functions and simple square roots

Beyond the *dlog*-case: elliptic integrals

- During the computation of the leading singularity, we can also bump into an elliptic curve

$$\int \frac{dz}{\sqrt{\mathcal{P}_4(z)}} \wedge d \log(\dots), \quad \mathcal{P}_4(z) = (z - a_1)(z - a_2)(z - a_3)(z - a_4)$$

- The leading singularity contains elliptic functions

$$\int \frac{dz}{\sqrt{\mathcal{P}_4(z)}} \propto K(\dots)$$

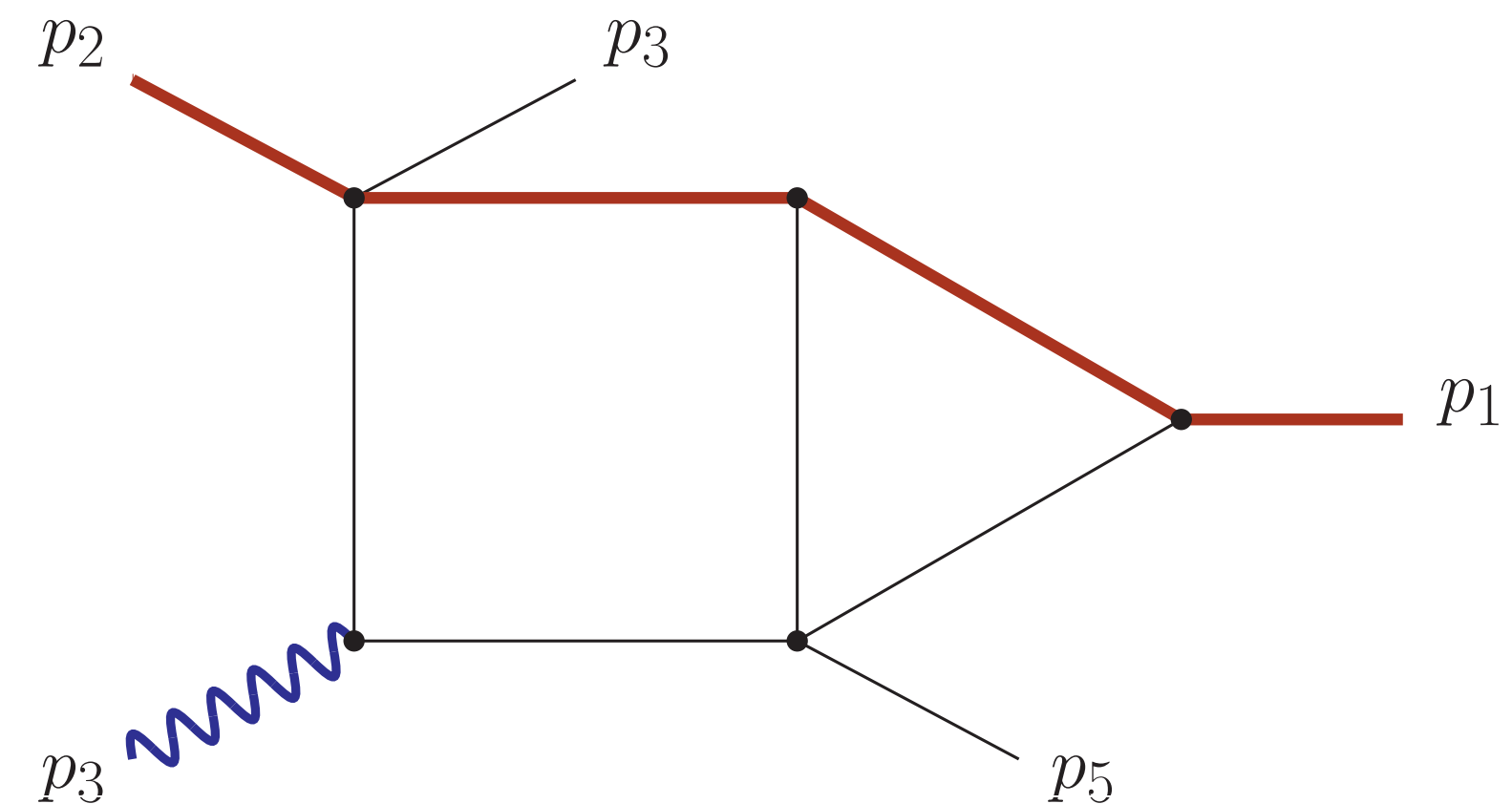
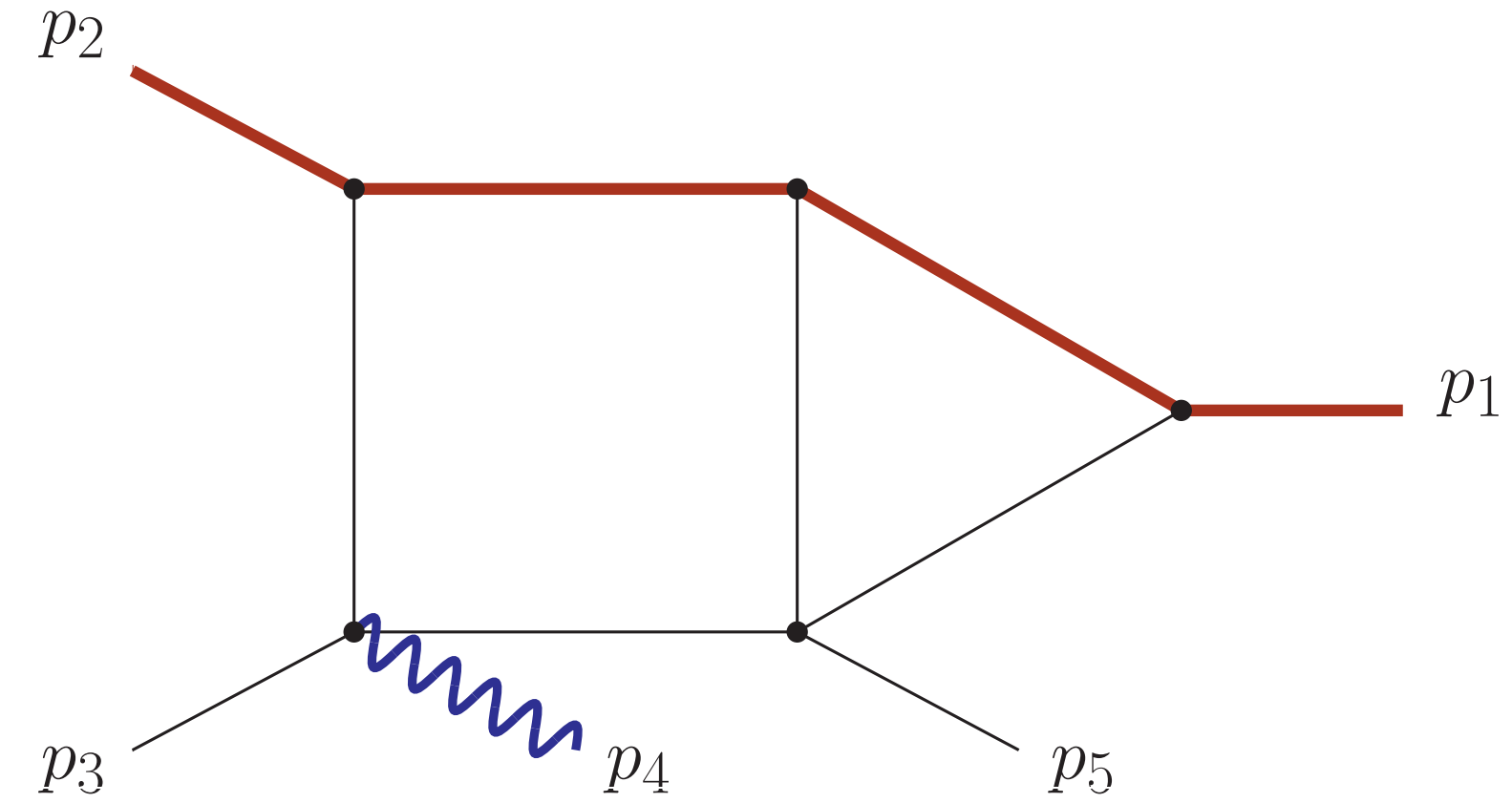
Elliptic integral
of the first kind



- Transcendental functions are needed to put the differential equation in canonical form
 - Progress on general strategy in recent years (see e.g. [\[Görges et al. 2023\]](#))
 - Still no general method to efficiently evaluate these functions

The “simple” $t\bar{t}W$ elliptic curves

- Comparable with known elliptic curves (e.g. [Badger et al. 2024])
- 4-point kinematics \Rightarrow depend on less than 7 variables
- 3 MIs for each sector
- Elliptic curve of the form
$$\mathcal{P}_4(z) = (z - m_t^2)(z - 3m_t^2)\mathcal{P}_2(z)$$
- The curves are distinct, as we checked by computing the j-invariant

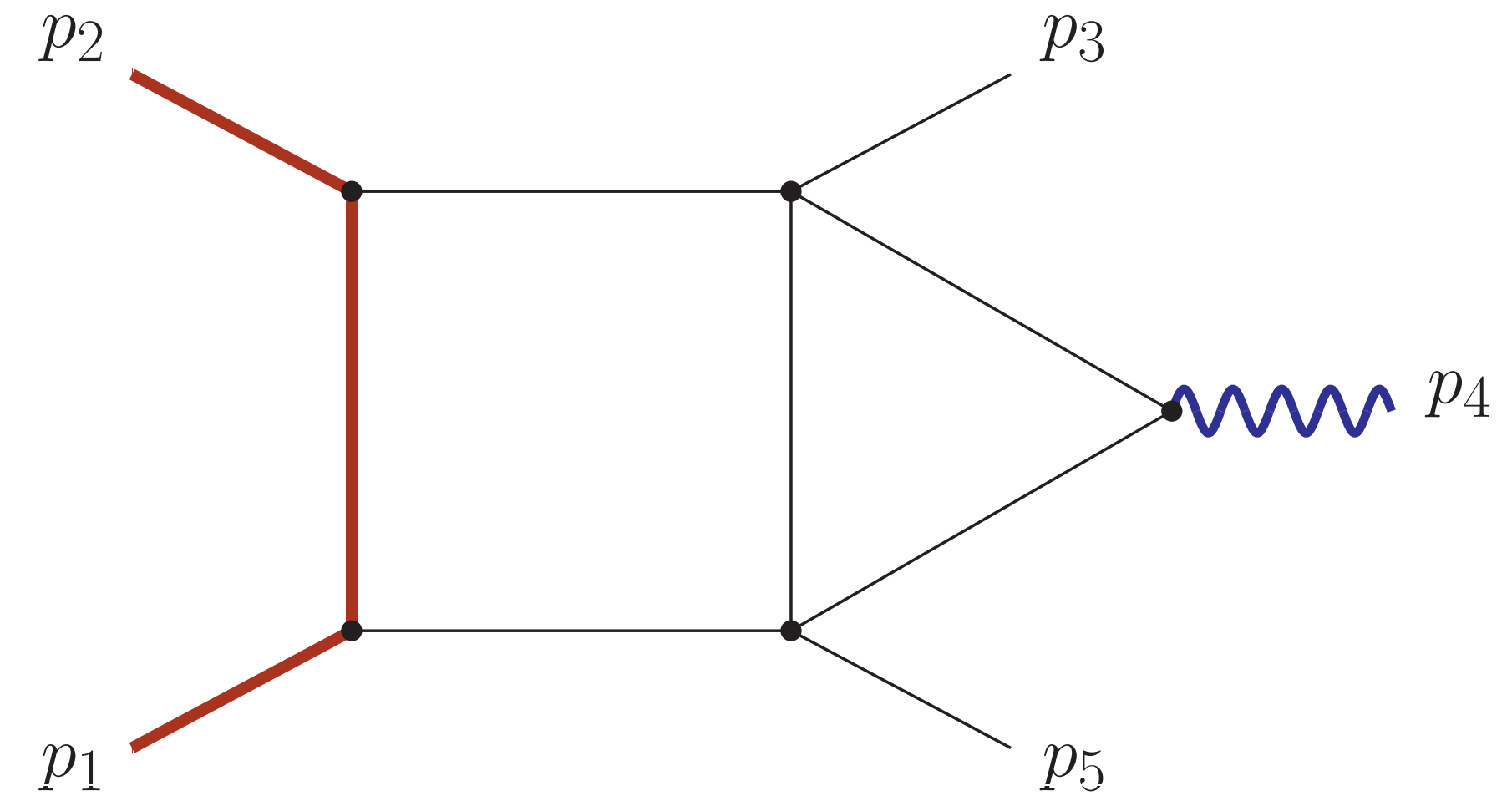


The “monster” $t\bar{t}W$ elliptic curve

- First ever study of an elliptic curve for a 5-point kinematics \Rightarrow dependence on all 7 invariants
- 7 MIs in the sector
- Computation of LS leads to

$$\int \left(\frac{dz}{\sqrt{Q_4(z)}} \wedge d \log(\alpha(y, z)) - \frac{dz}{\sqrt{Q_4(z)^\dagger}} \wedge d \log(\alpha(y, z)^\dagger) \right)$$

Same j -invariant \Rightarrow same elliptic curve



$$f^\dagger \equiv f|_{r_1 \rightarrow -r_1}, \quad r_1 = \sqrt{G(p_1, p_2, p_3, p_4)}$$

Algebraic complexity of the monster curve

- $Q_4(z)$ has degree 4 in z and degree 14 in \vec{x} , involves r_1 and 2787 terms
- Discriminant of the elliptic curve contains a degree 14 polynomial in \vec{x}
 - 2547 terms
 - File size is 94 KB
 - Appears in the denominators of the DEs \implies one of the singularities of the solution
- ε -factorised DEs challenging even with known techniques

How we deal with elliptics

Aims: obtain a good basis compatible with `DiffExp`

● Simple ε -dependence

- No ε -poles in the differential equation
- Maximum degree as low as possible (2 in this case)

● Elliptic MIs finite

- Poles of the amplitude dictated by tree-level and 1-loop: no elliptic functions
- Allows to apply the method of [\[Badger et al. 2025\]](#) to construct a basis of special functions up to the finite part



Apparent trade-off between the above criteria and the algebraic complexity:

We allow for a spurious degree-9 polynomial in the denominators

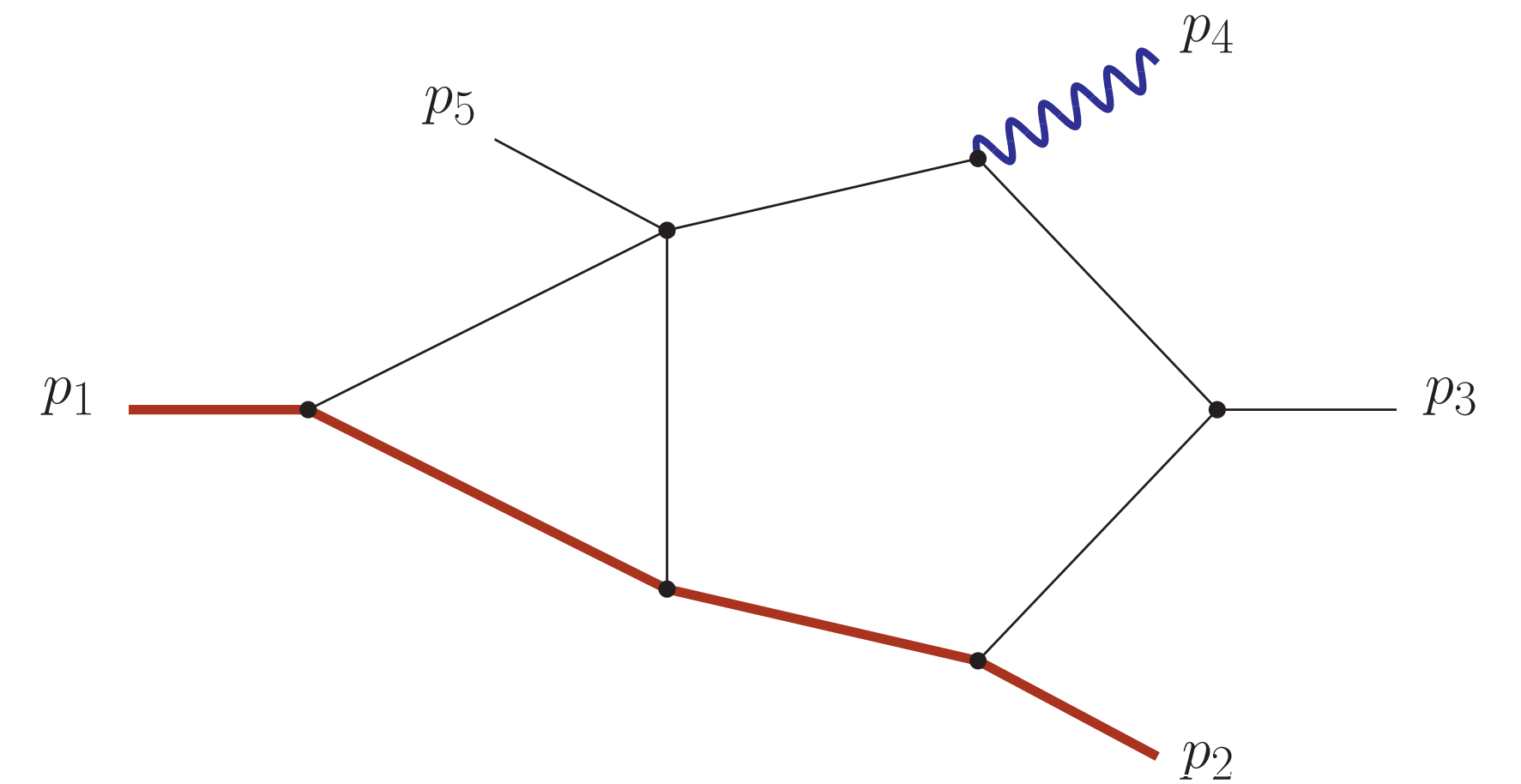
Beyond (?) the *dlog*-case: nested square roots

- For $t\bar{t}H$ [Febres Cordero et al. 2024] and $t\bar{t}j$ [Badger et al. 2024] leading singularities involving nested square roots were observed. This is the case also here

$$NR_{\pm} = \sqrt{q_1(\vec{x}) \pm q_2(\vec{x})r_1}, \quad r_1 = \sqrt{G(p_1, p_2, p_3, p_4)}$$

$$NR_+ \xrightarrow{r_1 \rightarrow -r_1} NR_-$$

- Nested square roots are not supported by DiffExp
 - Due to the elliptics, the differential equation will not be ε -factorised anyway
- \implies keep the differential equation linear in ε



Final representation of the differential equation

⊙ We selected a basis

- ε factorised as much as possible
- Linear in ε for the nested square root sectors and at most quadratic in the elliptic sectors
- Elliptic integrals finite

⊙ Write connection matrix in terms of independent one-forms

$$d\vec{I}(\vec{x}; \varepsilon) = dA^{(F)}(\vec{x}; \varepsilon) \cdot \vec{I}(\vec{x}; \varepsilon), \quad dA^{(F)}(\vec{x}; \varepsilon) = \sum_{k=0}^2 \varepsilon^k \left[\sum_{\alpha} c_{k\alpha}^{(F)} d \log(W_{\alpha}(\vec{x})) + \sum_{\beta} d_{k\beta}^{(F)} \omega_{\beta}(\vec{x}) \right]$$

Some numbers...

	Nested square root sectors	"Simple" elliptic sectors	Monster elliptic sector	# square roots	# letters	# one-forms	Dimension one-forms file
Family 1	Yes	2	No	8	101	119	6.7 MB
Family 2	No	1	Yes	11	122	84	311 MB
Family 3	No	1	Yes	12	137	96	316.5 MB

Numerical checks

- DiffExp implementation with in-house path-parametrisation
- Checked against AMFlow at 10 physical phase-space points, to 25 digits accuracy
- We verified that we can integrate between any of these 10 points with DiffExp

Summary and Outlook

- ① Basis and differential equation for all the integral families relevant for $t\bar{t}W$ production at 2-loop at leading color
- ① Addressed complications arising from nested square roots and elliptic integrals
- ① Semi-numerical solution using `DiffExp`
- ① Next steps
 1. 2-loop amplitude
 2. ε -factorised differential equation

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Thank you!

Backup slides

Definitions for elliptic curves

- Cross ratio

$$\lambda = \frac{(a_1 - a_4)(a_2 - a_3)}{(a_1 - a_3)(a_2 - a_4)}$$

- Elliptic integral of the first kind

$$K(\lambda) = \int_0^1 \frac{dt}{\sqrt{(1-t^2)(1-\lambda t^2)}}$$

- Periods of the elliptic curve

$$\omega_1 = 2c_4 \int_{a_2}^{a_3} \frac{dz}{y} = 2K(\lambda), \quad \omega_2 = 2c_4 \int_{a_1}^{a_2} \frac{dz}{y} = 2iK(1-\lambda),$$
$$\text{with } c_4 = \frac{1}{2} \sqrt{(a_1 - a_3)(a_2 - a_4)}$$

- J-invariant

$$j = 256 \frac{(1 - \lambda(1 - \lambda))^3}{\lambda^2(1 - \lambda)^2}$$